



Portfolio

Tobias Härdtlein

B.A. industrial design

2022

Tobias Härdtlein

Education

HTW Berlin university of applied science

Berlin | 09/2015 - 05/2021
Industrial design B.A.
grade 1.5

University of Cincinnati

Cincinnati | Fall 2018
Student exchange program

LMU Ludwig-Maximilians-University

Munich | 09/2013 - 08/2015
Media-computer-science B.Sc.
2.5 years of study

Highschool Kempfenhausen

Starnberg / Munich | 09/1996- 07/2011
Abitur (high school degree)

Permanent Address Sonnenweg 9
82335 Berg
Germany

Cell +49 178 1486240

Experience

Costaboard

Berlin | 05/2021 - 01/2022 | *Head of Product Design*
Research and product development. Concept and design of new products. Support of manufacturing up to series production. Project management of new product developments.

Infrar3d

Berlin | 06/2021 - 11/2021 | *Industrial Designer*
Planning, design, programming and engineering of prototypes to market maturity. Includes team organization and collaboration.

Blackjack lighting

Chicago | 1/ 2019 - 5/2019 | *Internship / Junior Designer*
Design and engineering of lighting track systems. Environmental rendering, assist the development of marketing material. Layout of custom fixtures for commercial applications.

Town Hall of Starnberg

Starnberg | 11/ 2013 - 10/2015 | *Event Technician*
Planning, preparation and execution of light, sound engineering and safety regulations for concerts, fairs and congresses. Finally the supervision of the events.

UNIKAT#shirts

Munich | 2006 - 2015 | *Entrepreneurship*
Established of my own clothes label „#UNIKAT„ in Munich. Design-development, screen printing, E-Commerce, Workshops and commissioned work.

e-mail tobi@haerdtlein.team

Web haerdtlein.team

Skills

Analog

Prototyping | Sketching | Model Making
Wood- Plastic- Metal Shop working |
3D printing | Screenprinting | Photography | Problem-solving | Coding

Programs

SolidWorks | Rhino 3D | Grasshopper
Cinema4D | Keyshot | InDesign | Photoshop | Illustrator | Lightroom | Word | Excel

Languages

German native
English business fluent

Programming language

C ++ | Python | Java Script | HTML | CSS

Interests

Snowboarding | Sailing | Coding |
Construction work | Mechanics |
Traveling | Politics

Honor

Awards

European Product Design Award 2019
Bronze
Category Packaging Design/Food

World Star Student Award 2018

Certificate of Recognition
World packaging organization (WPO)

German Packaging Award 2017

young talent
German packaging institute (DVI)

1st Prize in the category UX 2017

PACKPLAY2
Université du Québec à Montréal

Exhibitions

Fachpack 2018

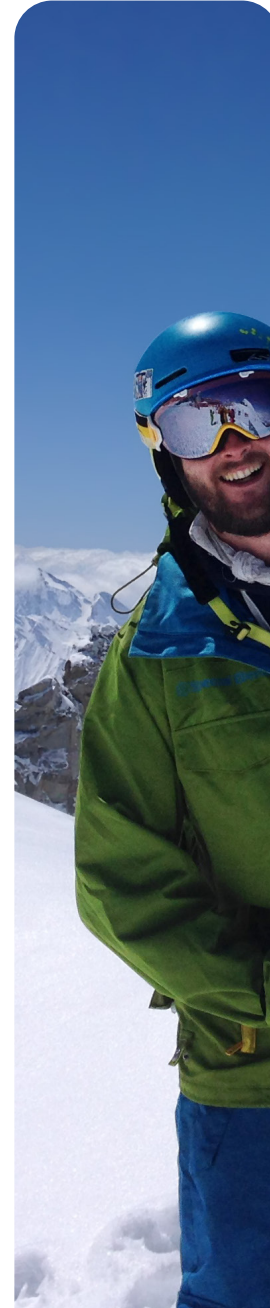
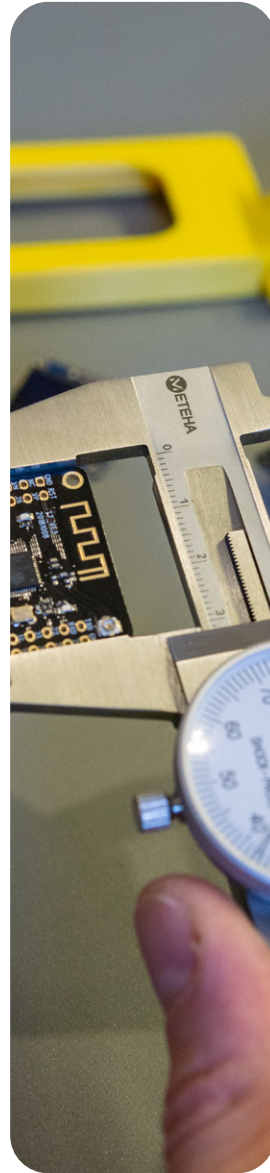
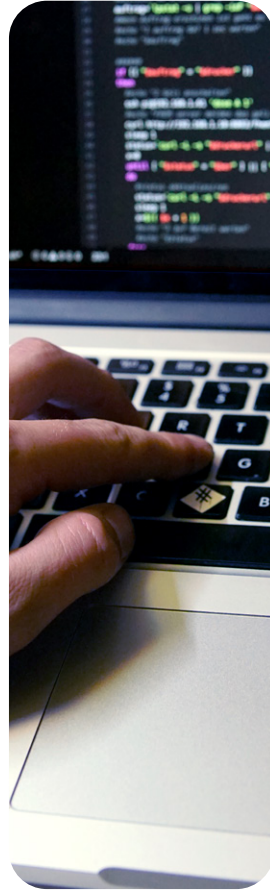
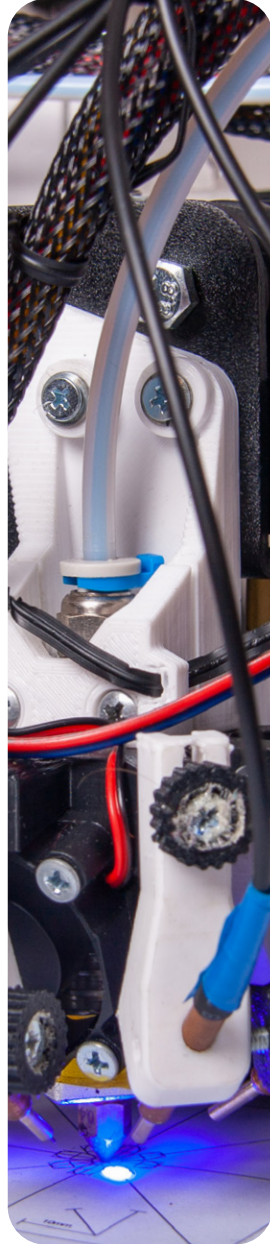
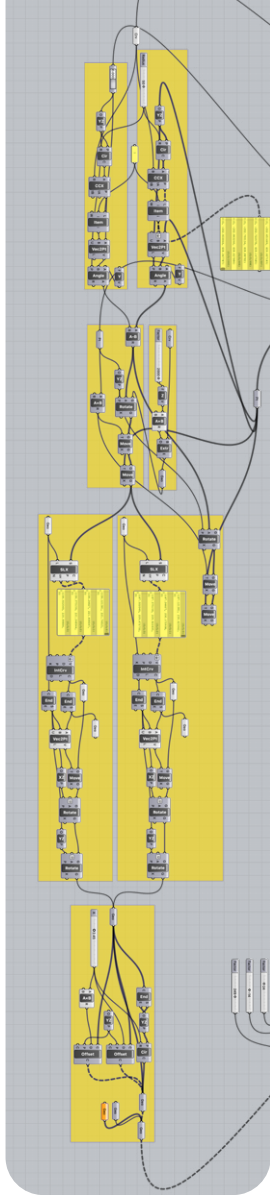
At the stand of Bayerndesign

Interpack 2017

At stand of WIPAK

Unterstrom 2017

Berlin design show



About me

I grew up in a family where everything was constantly renovated, rebuilt and improved: The house, the terrace, the boat... from an early age I knew how to use all kinds of tools. There was virtually nothing I couldn't fix.

That's why I'm an industrial designer: I want to make people's everyday lives better, easier, more intuitive. I am a problem solver.

This very everyday life is permeated by technologies - and I am a bit of a technology nerd (5 semesters of Media-computer-science studies). The core of my products is therefore often a combination of technology and elaborate mechanics.

Technology meets function meets aesthetics. My goal is complex design without being complicated.

When I design a new product, it leaves my head very quickly. I am someone who acts, builds, discards, tries new materials, codes, 3D prints, assembles, all over again... until it works.

Nothing goes without prototyping for me. I want to understand my product, down to the smallest detail.

That's me. All or nothing.

*"We humans are lazy,
especially when it comes to
carrying groceries
home from the store"*



Carey

Autonomous transport assistance
for private use

Constructed with: Rhino3D | Grasshopper

Rendered with: Cinema4d

model: 3D Print

*54% of metropolitans go shopping on foot
48.7% buy groceries online, because
their purchases are too heavy for them.*

What if the purchase...



follows you,...



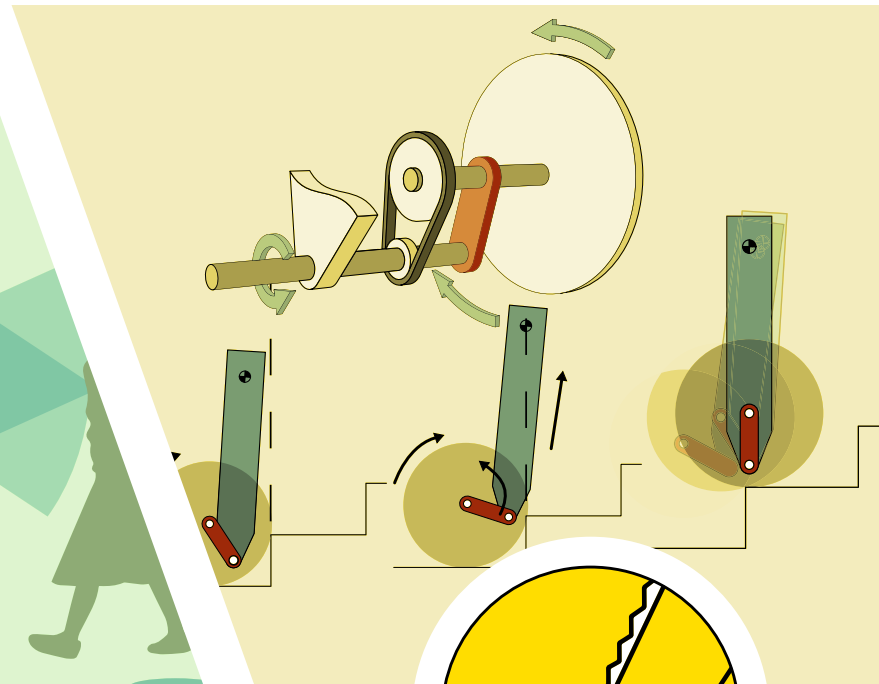
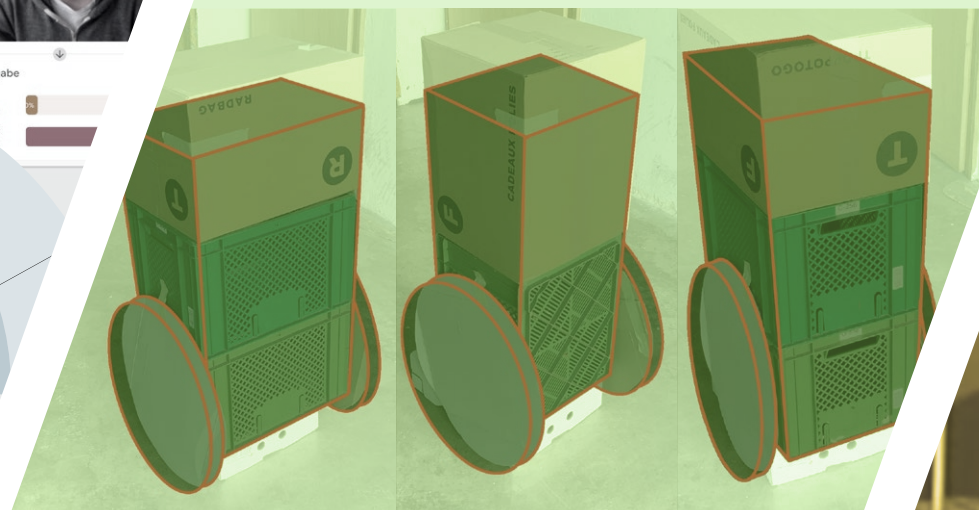
*integrates with
the human
environment...*

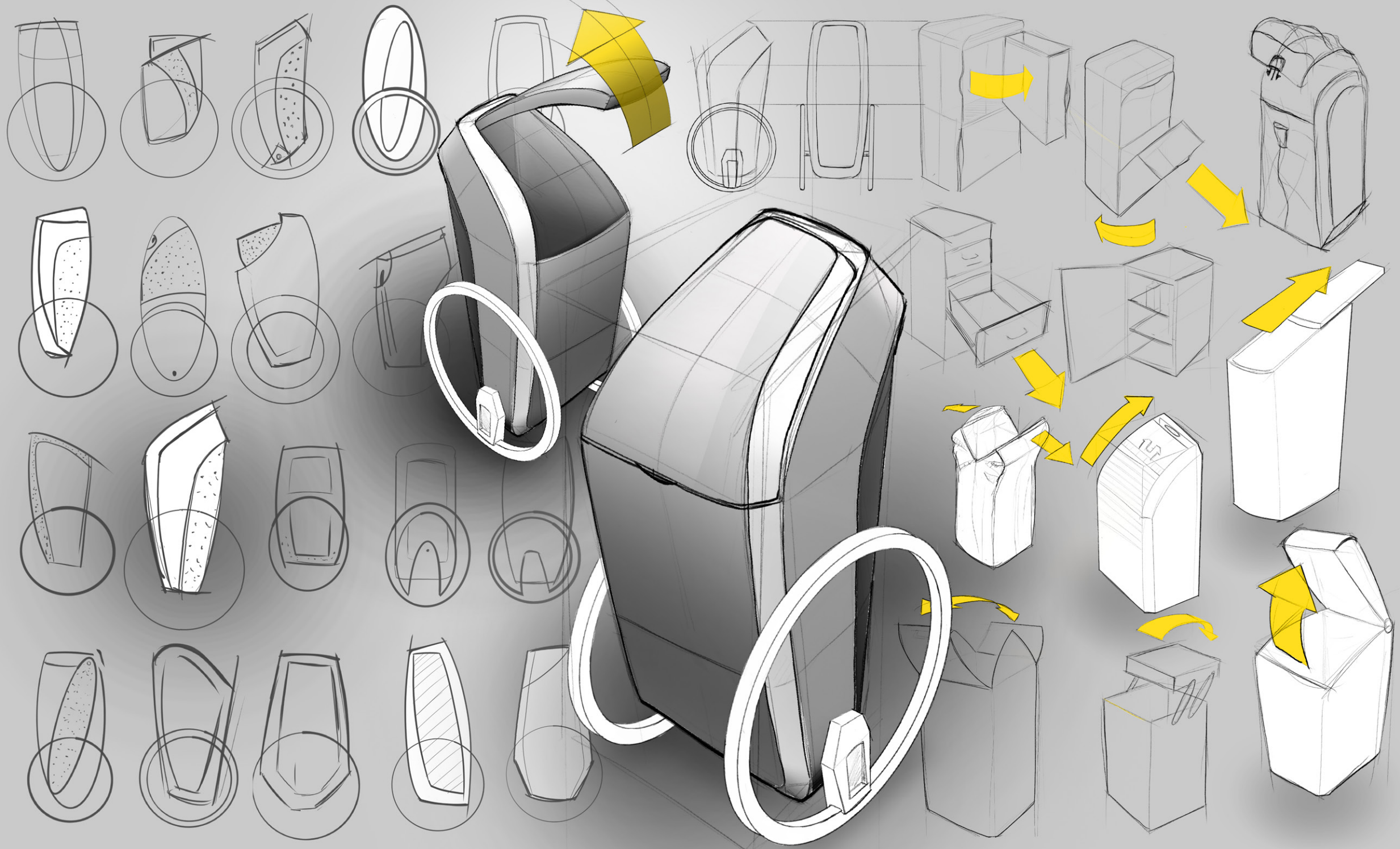


*and is able to climb
stairs and other
obstacles?*



Training interface for a computer vision model. It includes a 'Training' section with 'Modell ist trainiert', 'Erweitert', 'Epochen: 50', 'Batchgröße: 16', and 'Lernrate: 0,001'. There are two 'Ausgabe' (Output) sections showing 'Mit Brille' (with glasses) and 'Ohne Brille' (without glasses) for two different webcam inputs. A 'Webcam' input is also visible.

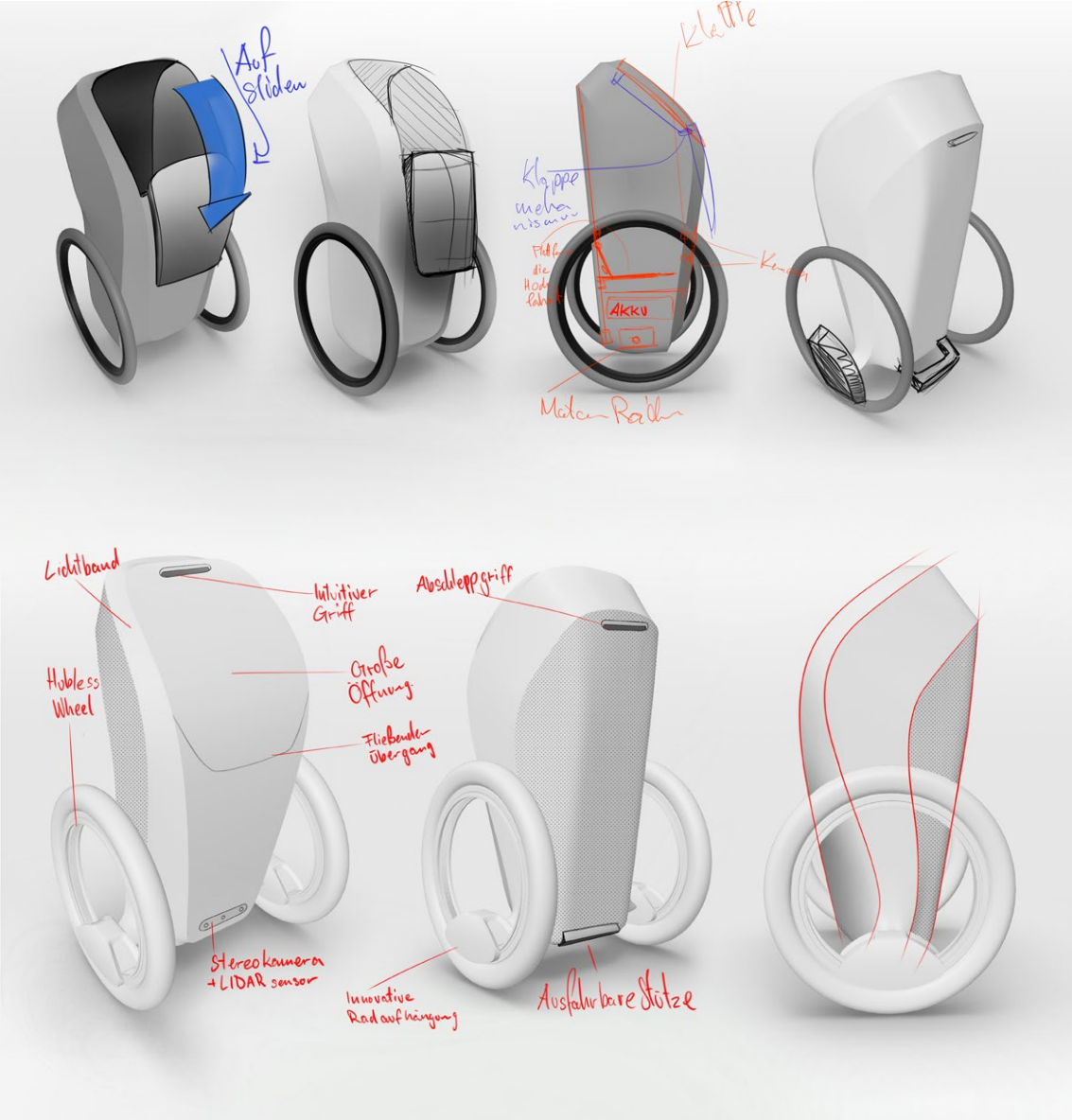




Shape development

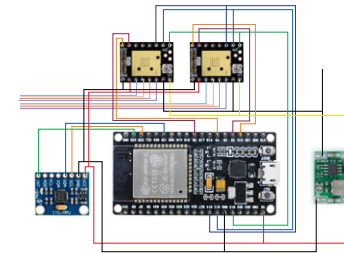
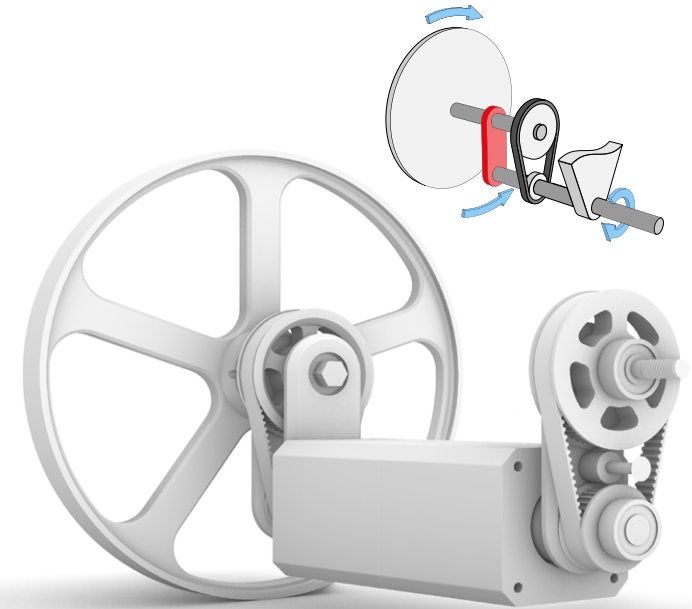


Using augmented reality sketching to define shape and appearance.



Prototype

Developing and testing the stair climbing function using a real self balancing robot.

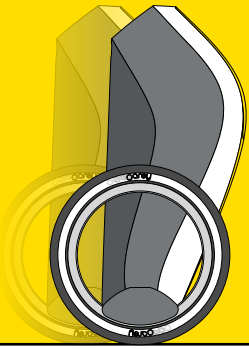


Self-built and coded control unit:

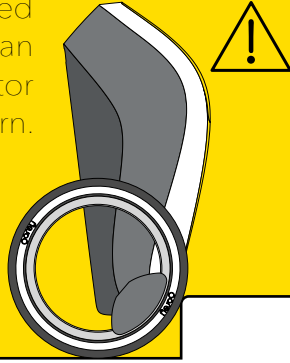
- Balancing on two wheels
- Controllable driving
- Stair climbing

vimeo.com/515034525

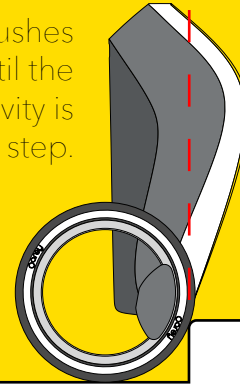




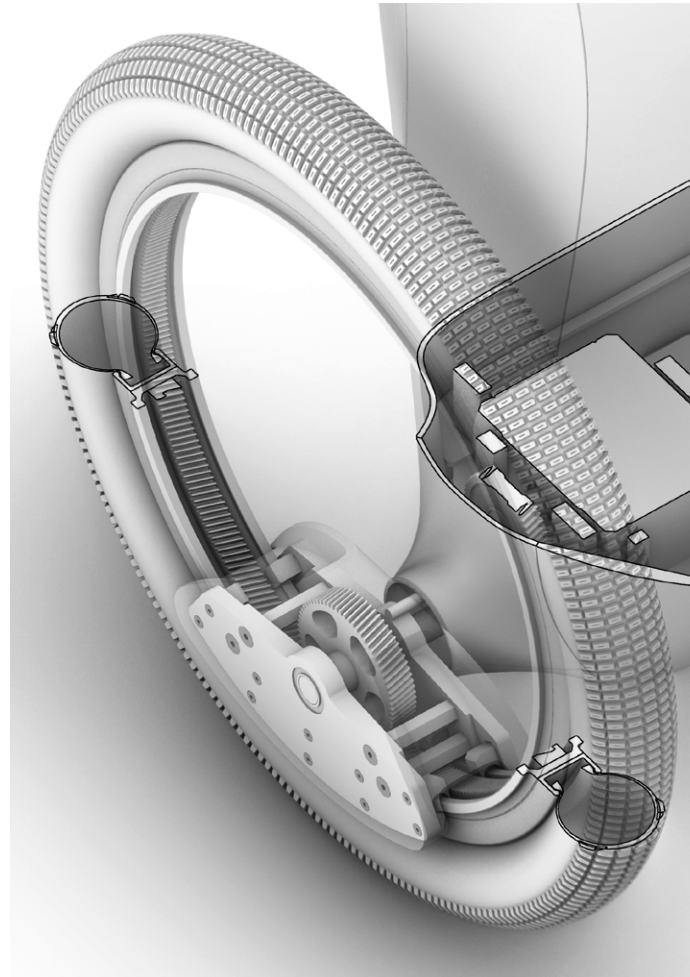
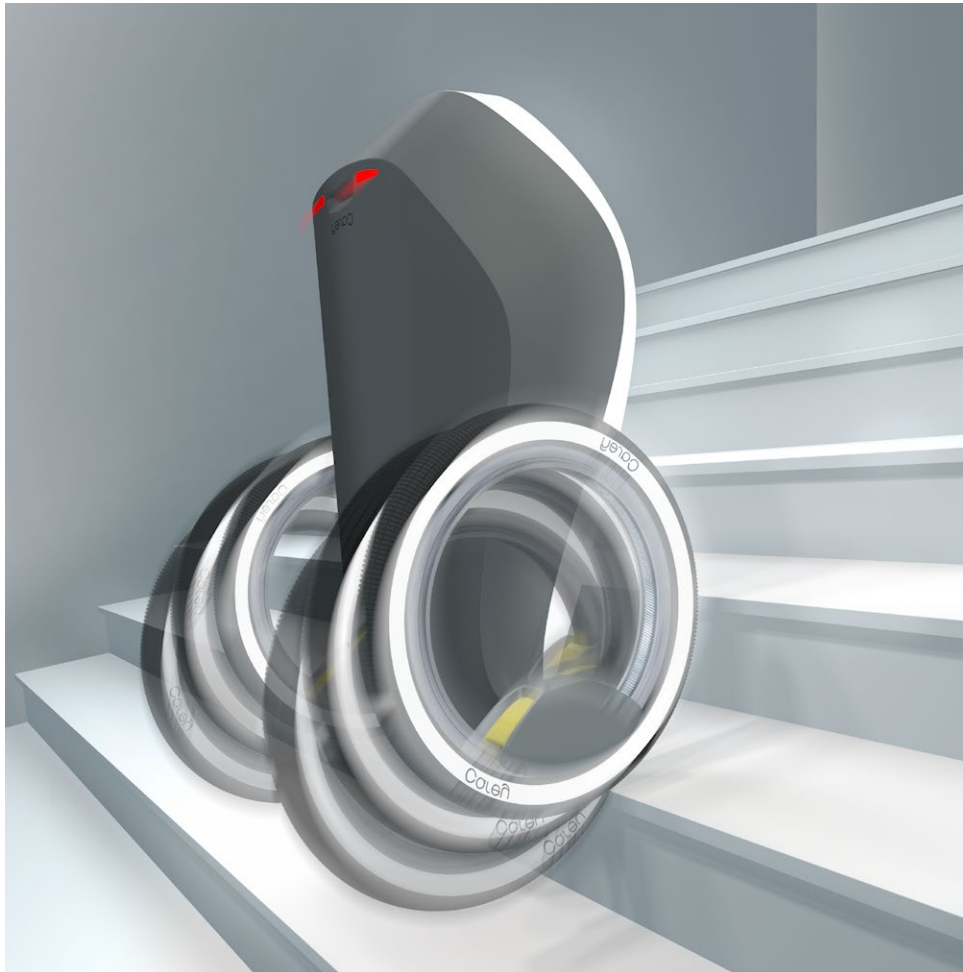
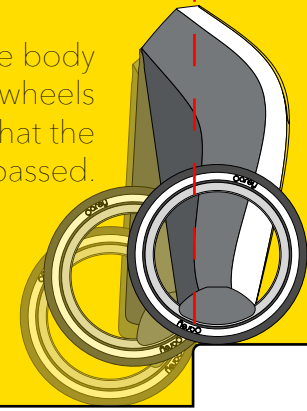
The wheel is blocked because of an obstacle but the motor continues to turn.



The body pushes upwards until the center of gravity is above the step.



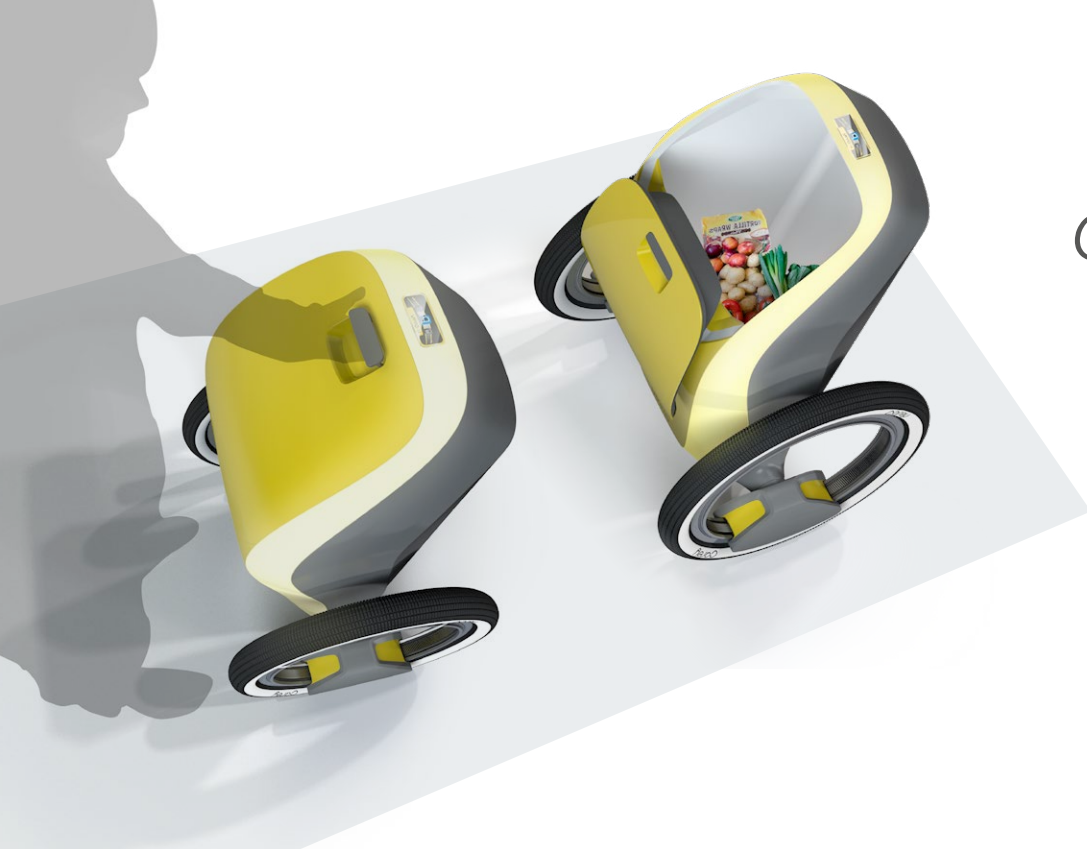
The mass of the body pulls the wheels behind it, so that the obstacle is passed.



Stair climbing

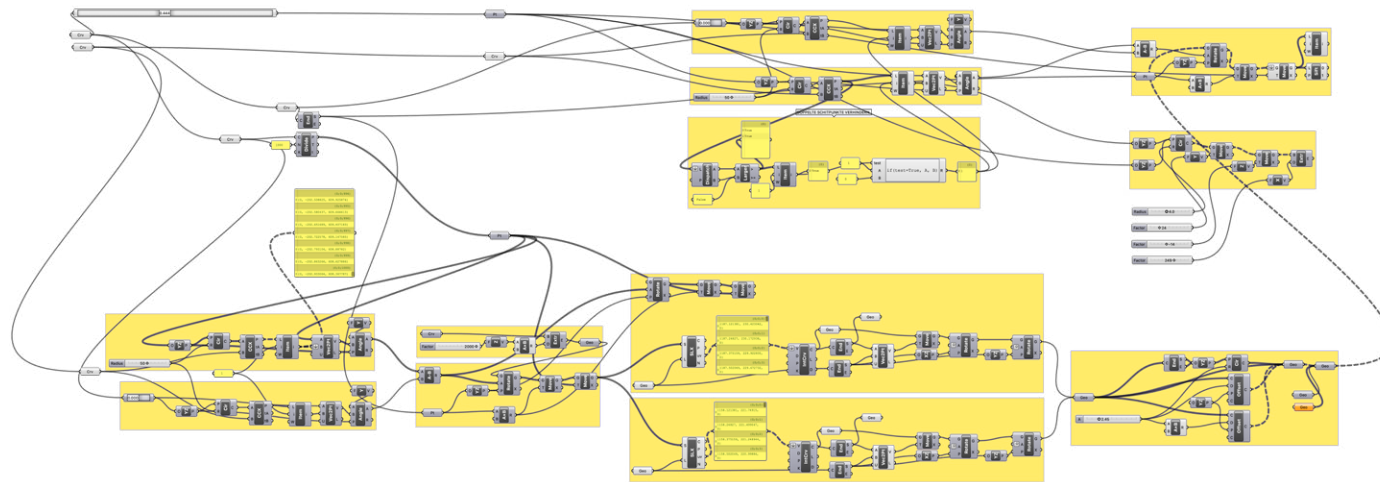
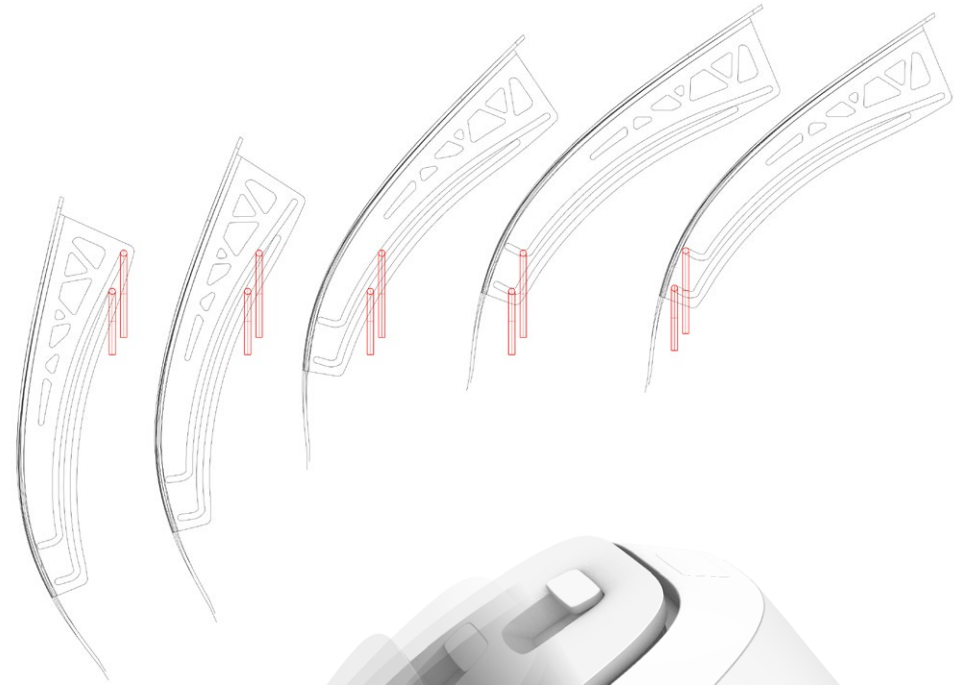
The hubless wheel is not attached to a center. This allows it to move more freely and enables the body to overcome obstacles.





Grasshopper

With Grasshopper, a two-rail door suspension was designed / simulated that opens as flat as possible so that it does not intrude during use.

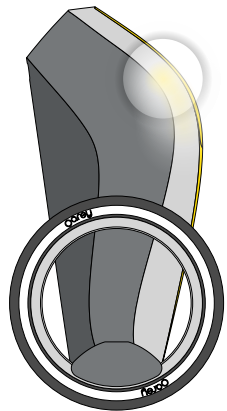
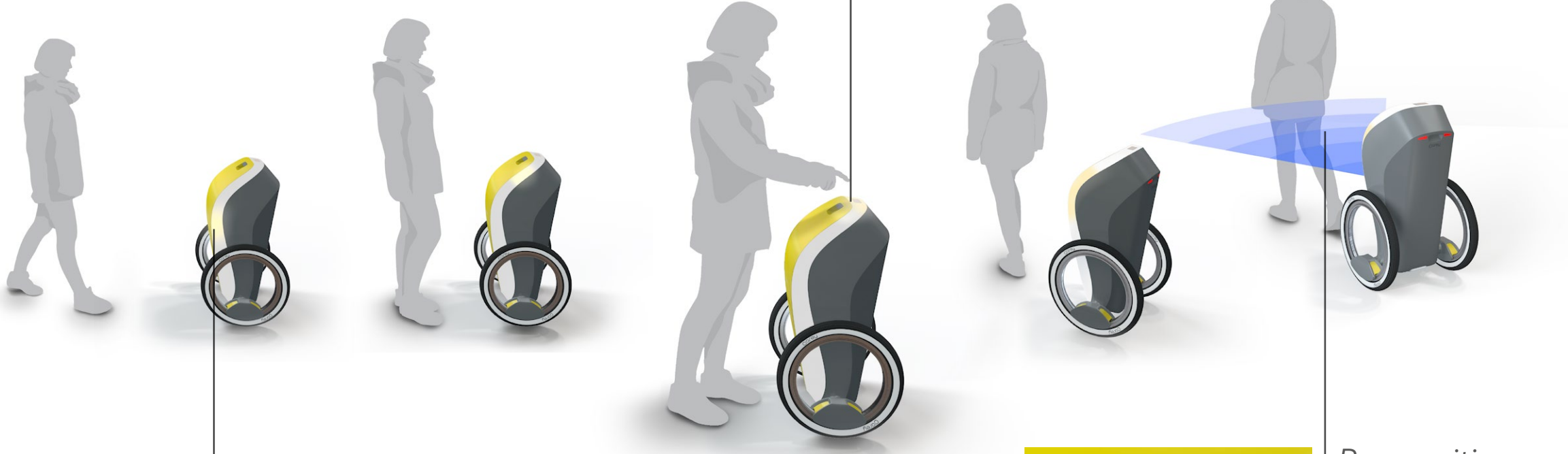


User Experience



Interface

Modes such as follow-me or parking can be selected via touchpad.

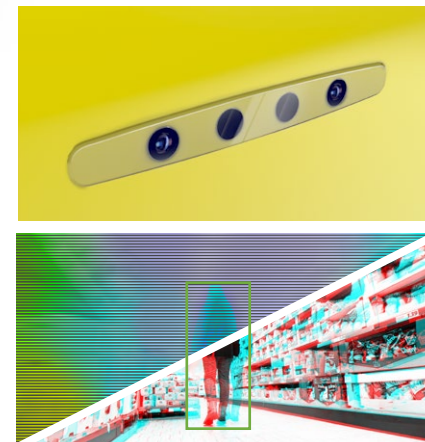


Interaction

The strip light interacts with the user. When he or she approaches, a light spot moves upward toward the touchpad.

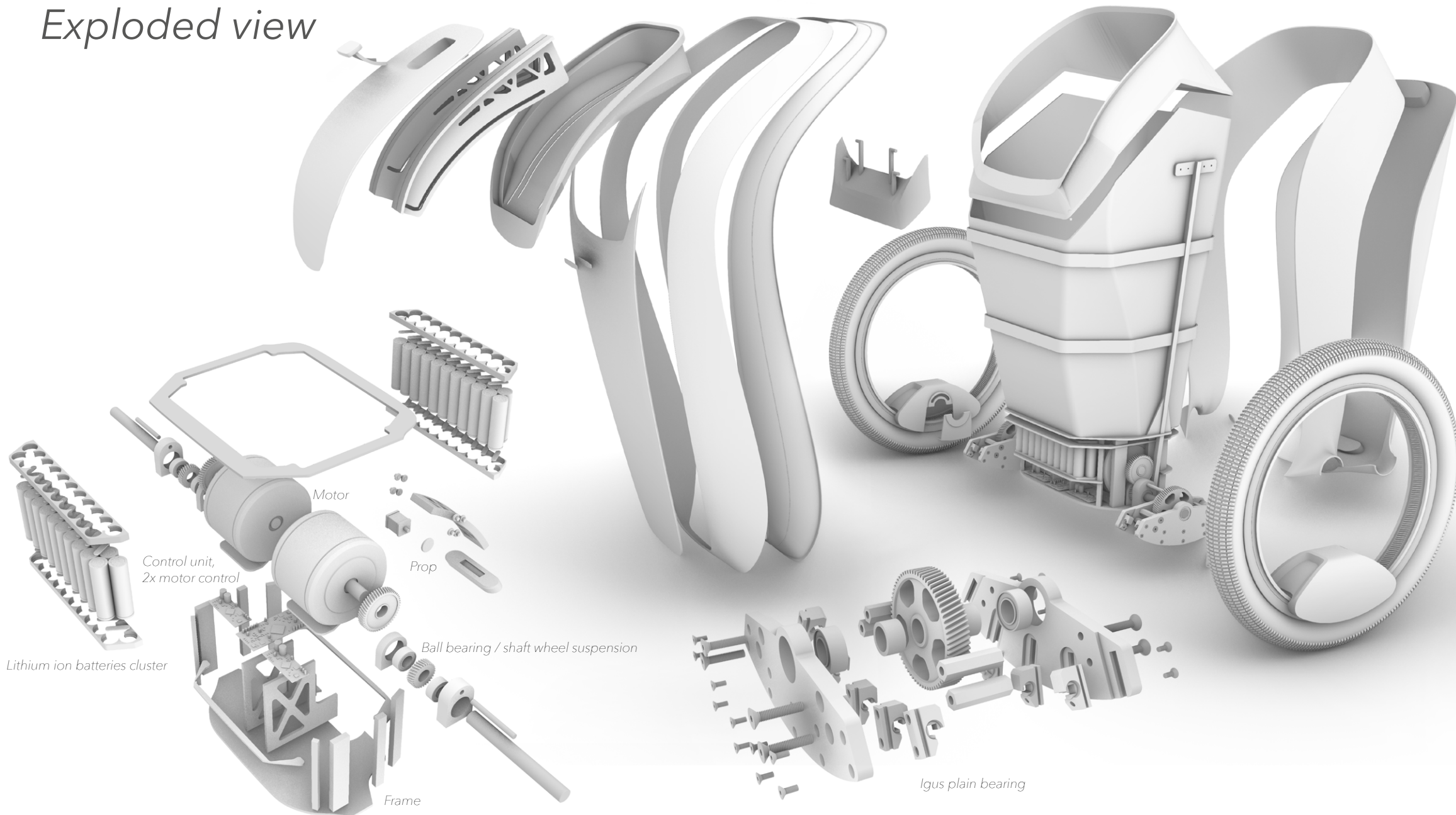
Recognition

Follow-me feature: Stereo cameras and LIDAR sensors provide spatial recognition and environmental perception.



Exploded view

Door handle
Door cover
Door rail
Casing door
Front shell
Light screen
Light reflector
Door hanger
Wheel
Container
Center shell
Rear shell



Motor
Control unit,
2x motor control

Lithium ion batteries cluster

Prop

Ball bearing / shaft wheel suspension

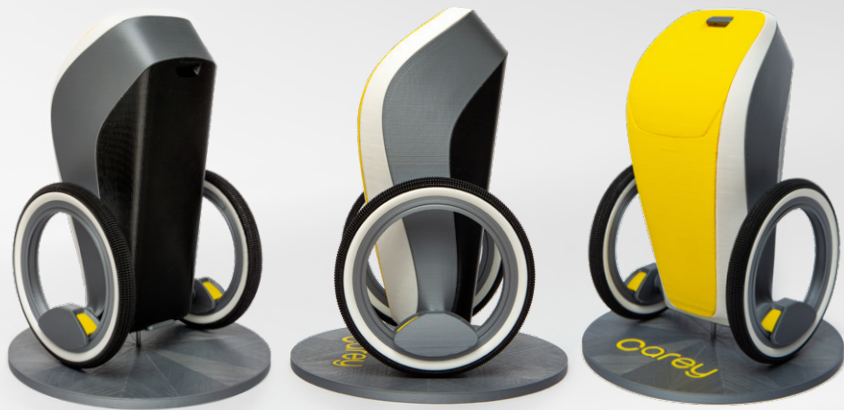
Frame

Iglus plain bearing

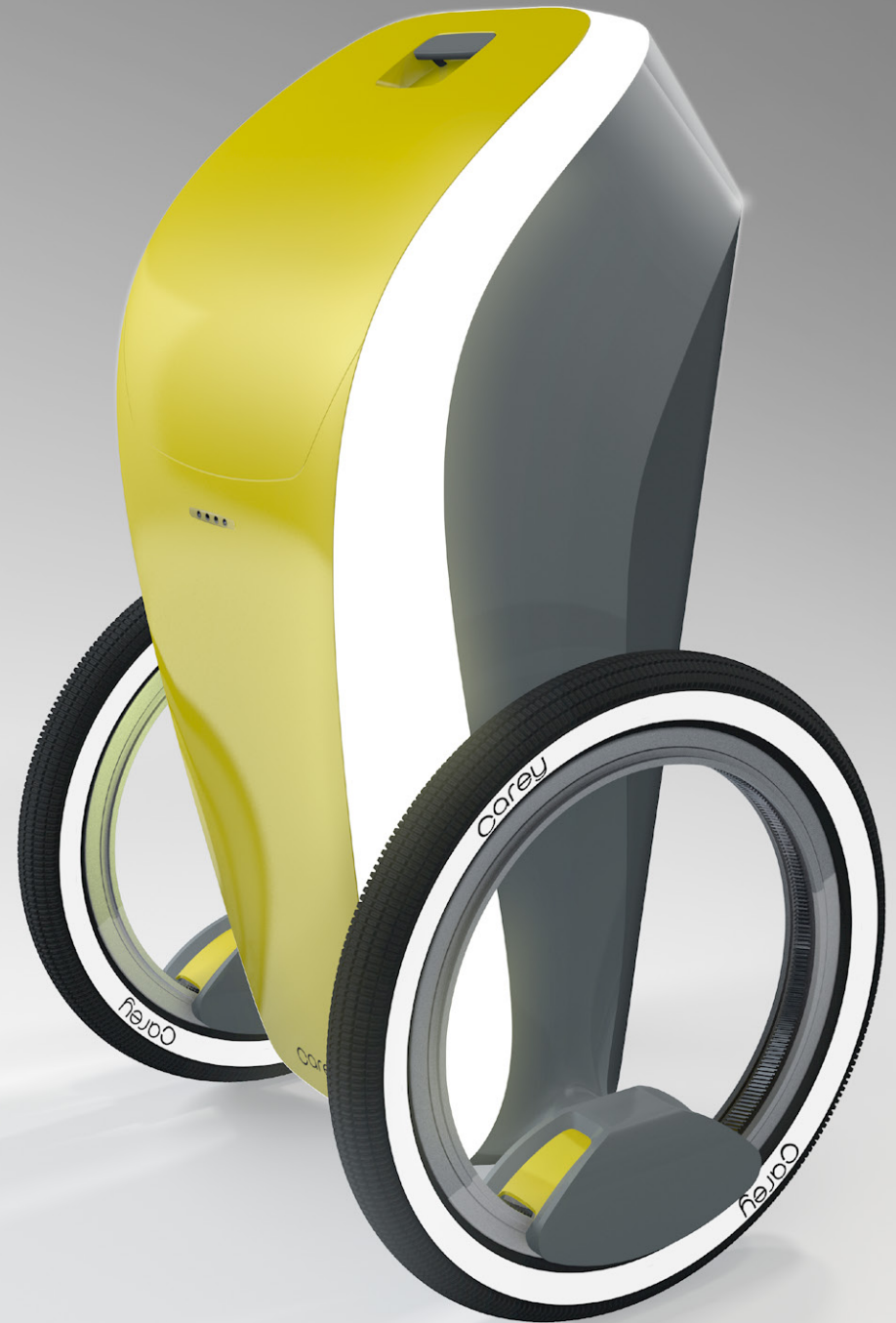




carey



3D printed model 1:20

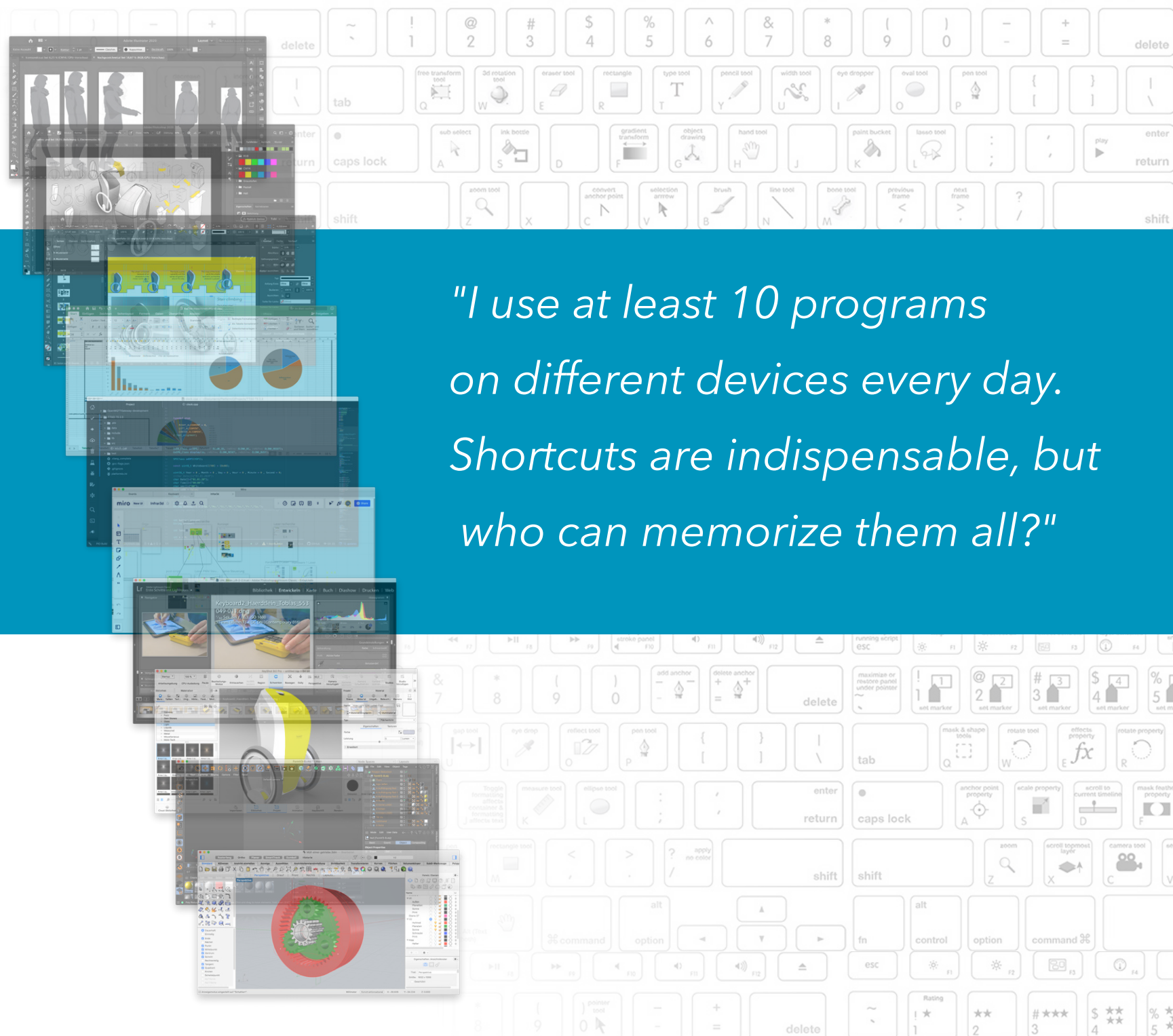


kībōdo

Macro keyboard for every device.

Constructed with: Rhino3D
Rendered with: Cinema4D
Model: 3D Print

*"I use at least 10 programs
on different devices every day.
Shortcuts are indispensable, but
who can memorize them all?"*

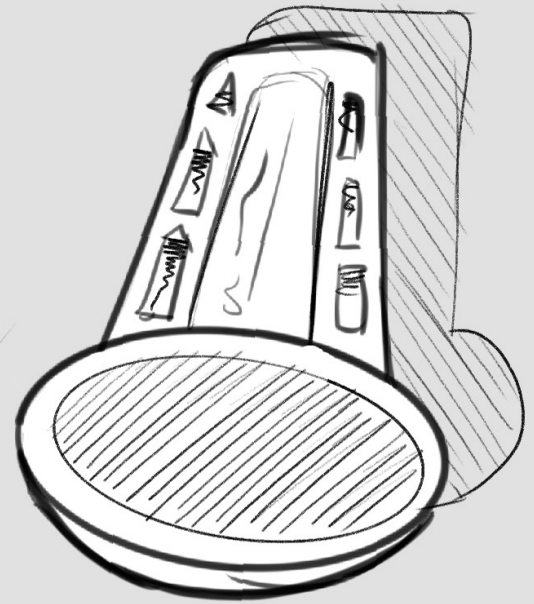


Rotary encoder!



E-ink!

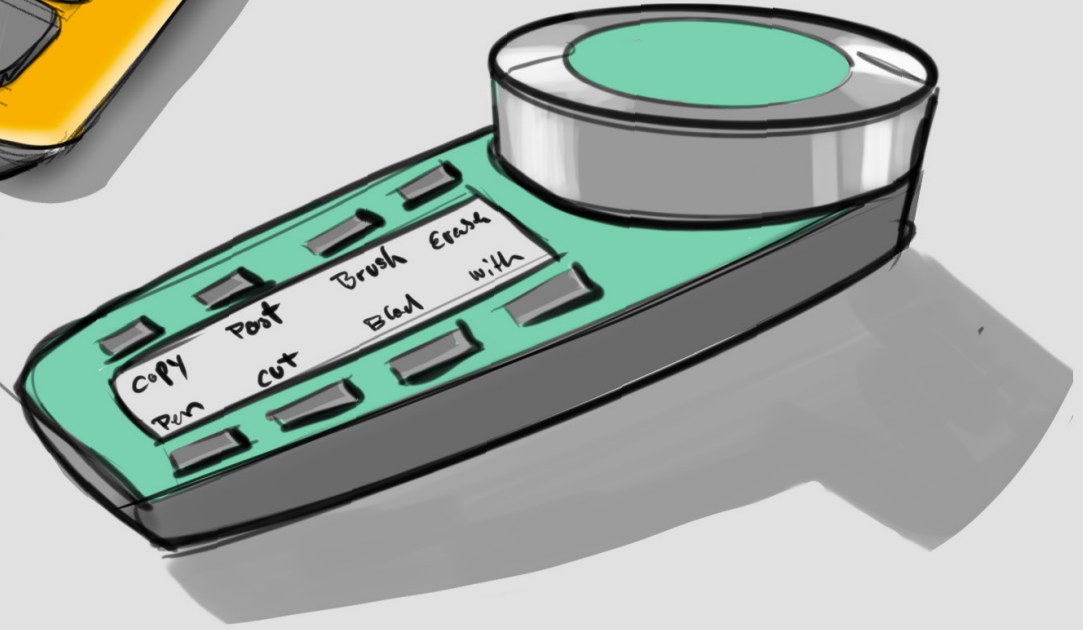
Real switches!



Like a calculator



encoder



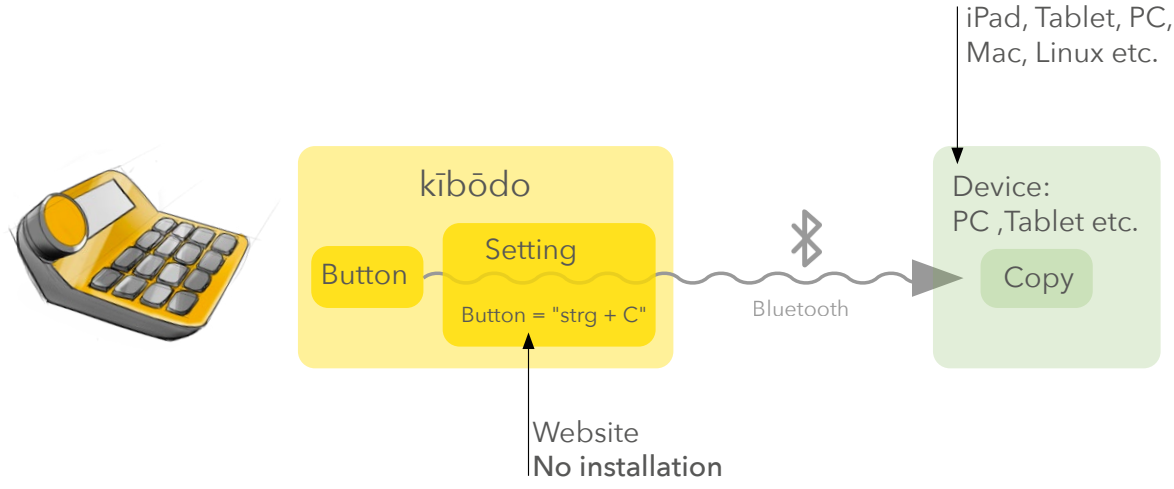
Products on the market

All are for PC/Mac only and need a software to be installed

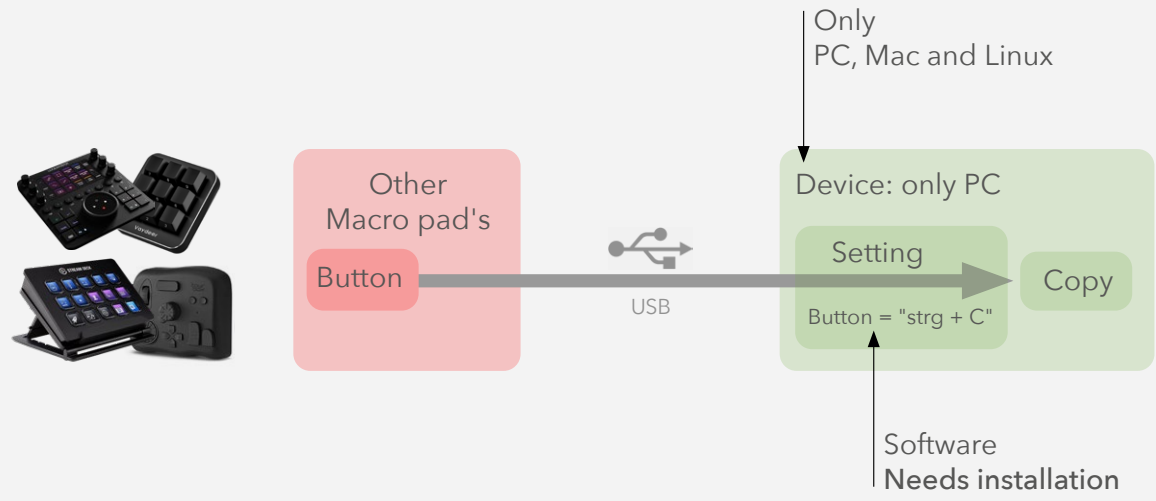


Name:	TourBox Elite	Elago Stream Deck	LOUPEDECK CT	Vaydeer Onehand Keyboard
Price:	190€	149€	499€	35€
Target group:	Creative	Streaming	Video editing	General
Buttons:	14	15	38	9
Rotary Wheel:	3	0	6	0
Pro's:	+Bluetooth +multifunctional keys	+Display / Keys	+Display / Touch	+Small
Con's:	- only PC/Mac - Software is needed - No Display	- only PC/Mac - Software is needed - Cable	- only PC/Mac - Software is needed - Cable	- only PC/Mac - Software is needed - Cable

Software concept

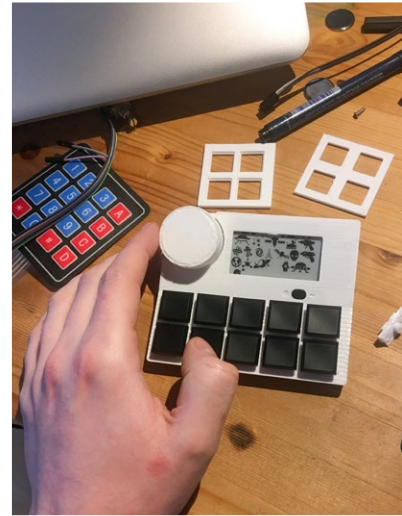
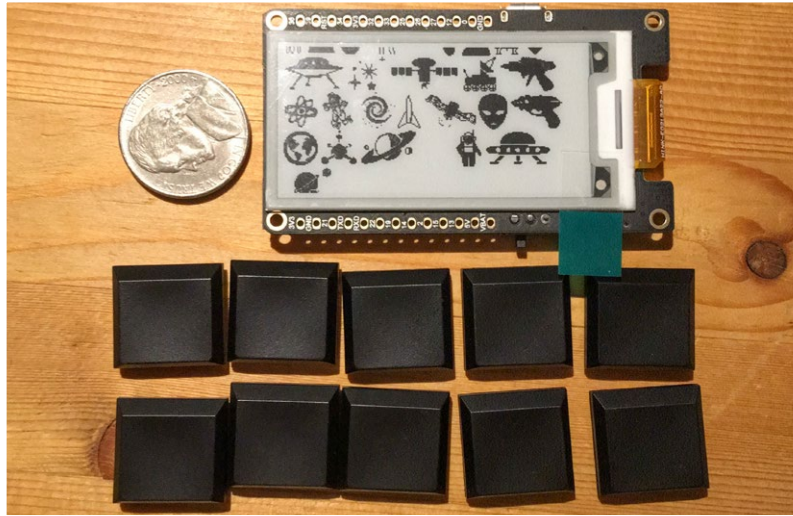


The buttons are assigned on the device, so it also works with an iPad. Each button can be used to simulate a keyboard and mouse input, as well as open files and URLs.

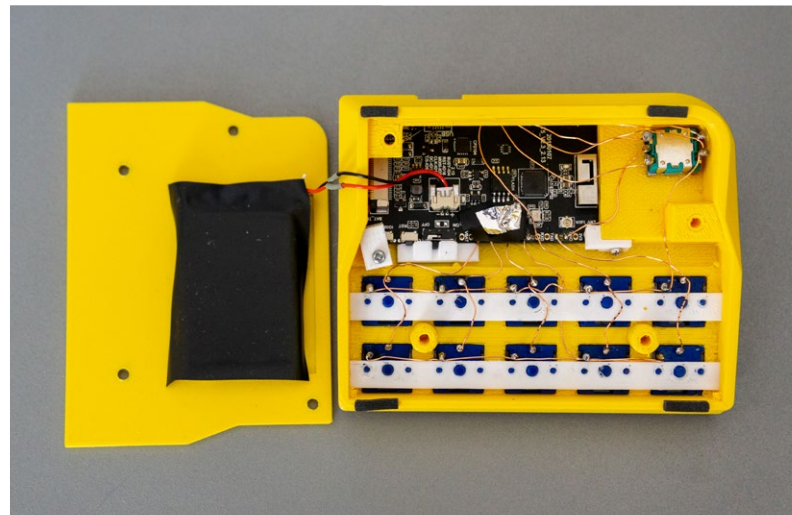
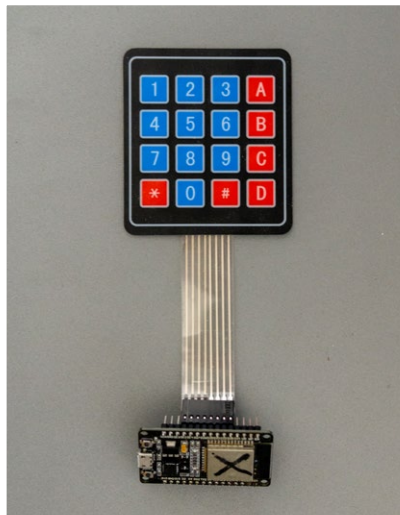


The keys are assigned on the customer's device, which is why it is not compatible with iPads.

Prototyping



Self built:
including encoder,
original key switch,
E-ink display
and battery in a
3D-printed case



Self coded:
2000 lines of
code, including
web server and
bluetooth HID
keyboard and
mouse driver.

```
main-v4.9.1.cpp -- ~/Documents/PlatformIO/Projects/Keyboard-BLE-main
C:\main-v4.9.1.cpp

void loop() {
    if((Keyboard.isConnected() == true) && (bleconnected == false)){
        // ist verbunden
        bleconnected = true;
        blestatus(true);
    }else if (Keyboard.isConnected() == false) && (bleconnected ==
        // ist nichtverbunden
        // Icon wegschicken
        bleconnected = false;
        blestatus(false);
    }

    keypad.getKeys();

    // die arbeits findet dort stat :
    // void keypadEvent(KeypadEvent key)

    rotary.loop();
    // die arbeits findet dort stat :
    // in rotaryAnMenu

    if (menu == 1){ // menu ende
        if (millis() - startzeit > autoexit){
            exitmenu();
        }
    }
    if (switchtoserver != "1"){
        unsigned long now = millis();

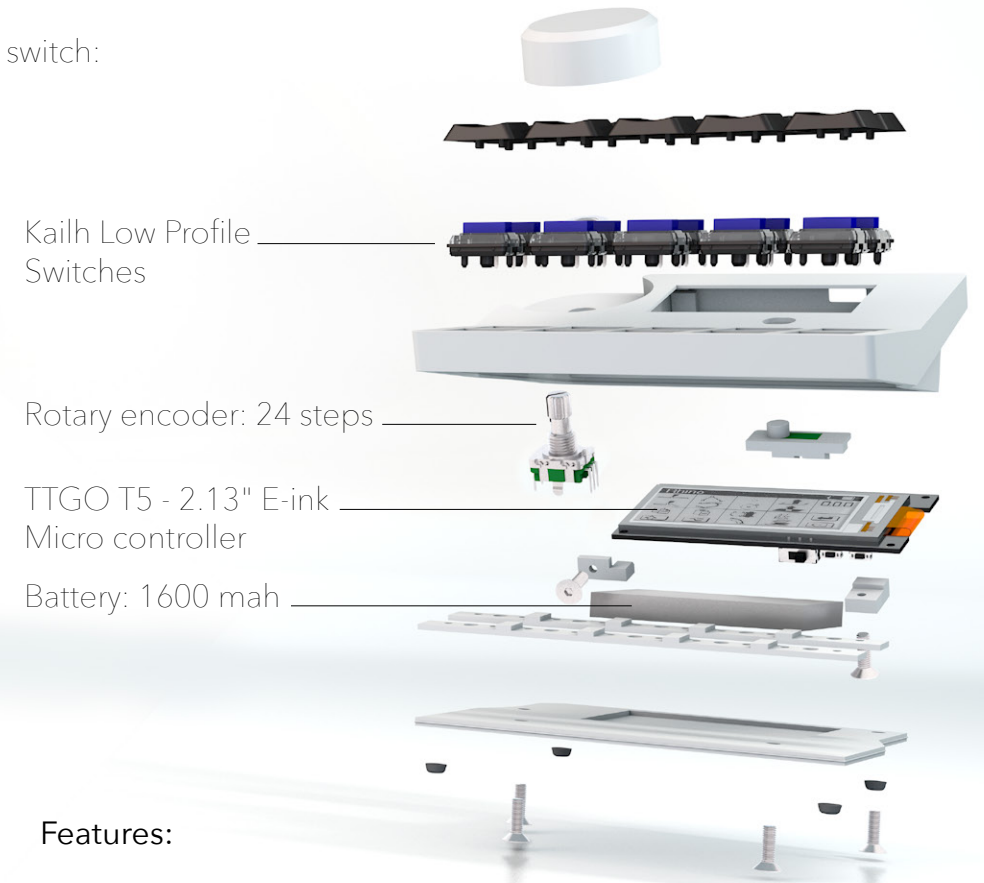
        if( (now - autoshtutdown) >= autoshtutdown){
            display.fillRect(47, 37, 158, 38, GxEPD_WHITE);
            display.fillRect(49, 39, 154, 34, GxEPD_BLACK);
            display.fillRect(58, 48, 158, 38, GxEPD_WHITE);
            displayText("Timeout Sleep", 68, CENTER_ALIGNMENT);
            display.updateWindow(47, 37, 158, 38, true);
            delay(1000);
            esp_deep_sleep_start();
            //ESP.deepSleep(0);
            delay(10000);
            //yield();

            //Serial.println("== Menu Stopp - timer");
        }

        if( (now - runtime) >= updatebat){ // alle 5 min //600000 //,
            measurelipo();
            runtime = now;
        }
    }

    void displayText(const String &str, uint16_t y, uint8_t alignment)
    {
        int16_t x = 0;
        int16_t x1, y1;
        uint16_t w, h;
        display.setCursor(x, y);
        display.getTextBounds(str, x, y, &w1, &h1, &w, &h);
        switch (alignment)
    }
}
```

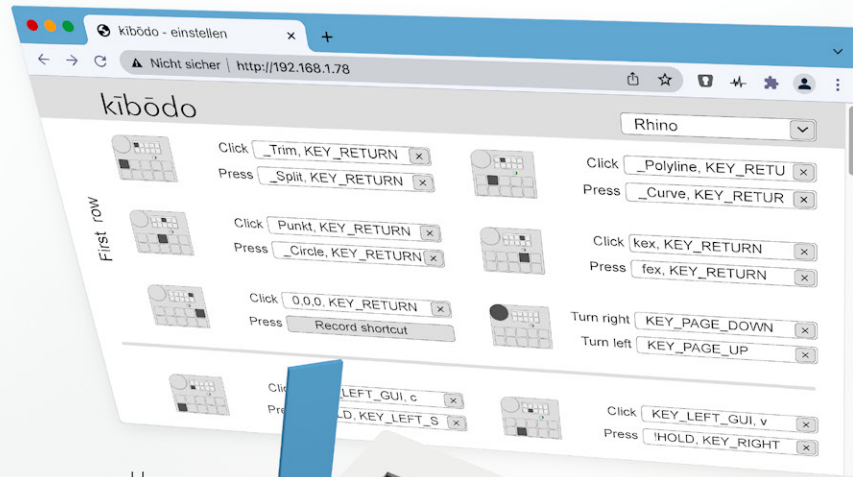
kībōdo



Features:

- Bluetooth keyboard and mouse
- 10 switches: click | long press | hold
- Each button freely assignable
- Rotary wheel with 24 steps per rotation
- 10 programs, settable via web page
- Eye friendly E-ink display
- Custom icons adjustable
- Compatible with PC and mobile
- Auto time out
- >15 days battery life

kībōdo



||
Press and hold
Starts the setting mode.
10 applications are
adjustable in the
website



|
Switch ON
&
Connect via
Bluetooth



|||
Press & Turn
to cycle through
the application



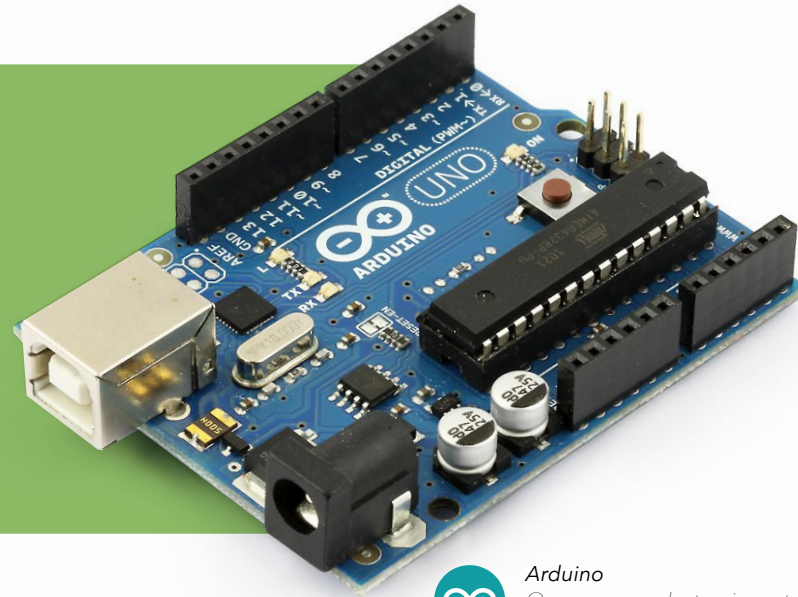
||||
10 buttons with 2 click types
and a rotary wheel allow up
to 22 programmable
functions per application



The E-ink display shows
the assignment
of the individual keys



„Lets Make it! - Develop a product of your choice. It should deal with the topic Arduino. A functional prototype is expected“



Pingju

Drawing on everything with everything

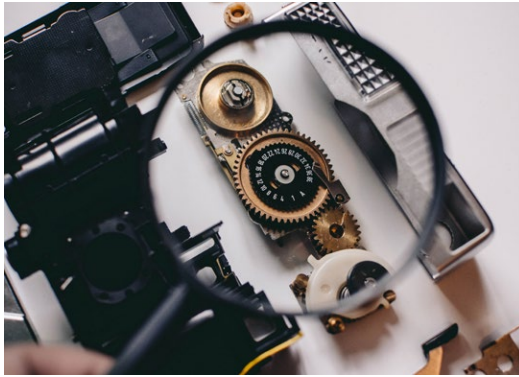
*Constructed with: Rhino3D
Rendered with: Cinema4d
Model: 3D Print
Size folded: 14x55x14 cm, unfolded : 55x55x14 cm
Work area: 30x30 cm*



Arduino

Open-source electronic prototyping platform enabling users to create interactive electronic objects

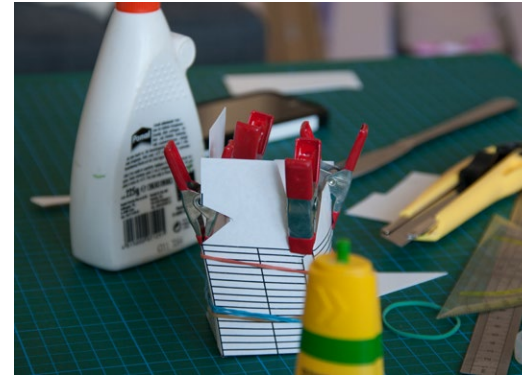
I would like to make something with...



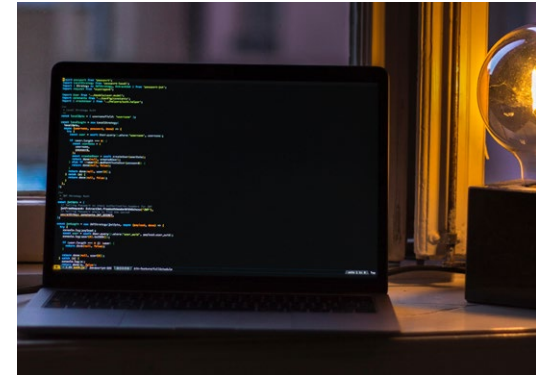
Mechanics



CNC Axis Technology



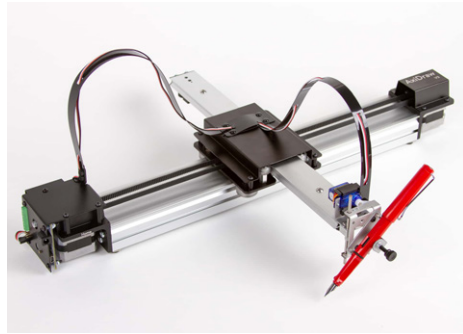
Model Making



Coding

... that supports me on my daily work. ... *that draws with everything on everything.*

Axidraw



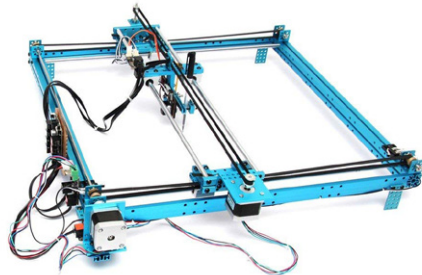
- ✓ Cool axes construction
- ✗ Big
- ✗ Software not userfriendly
- ✓ Every material
- ✗ Looks so technical

Hobby Plotter

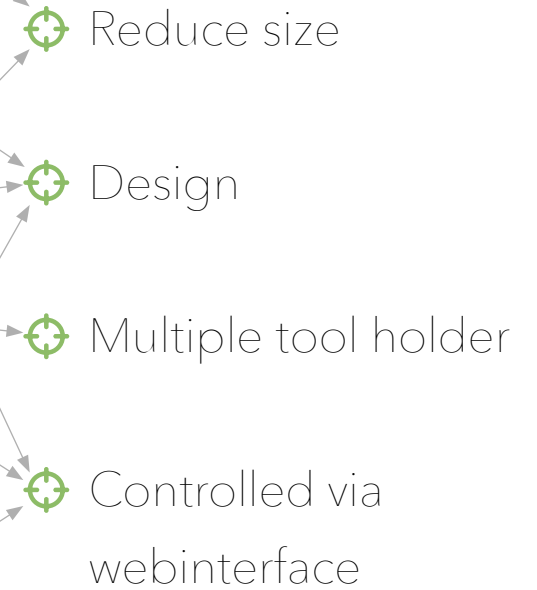


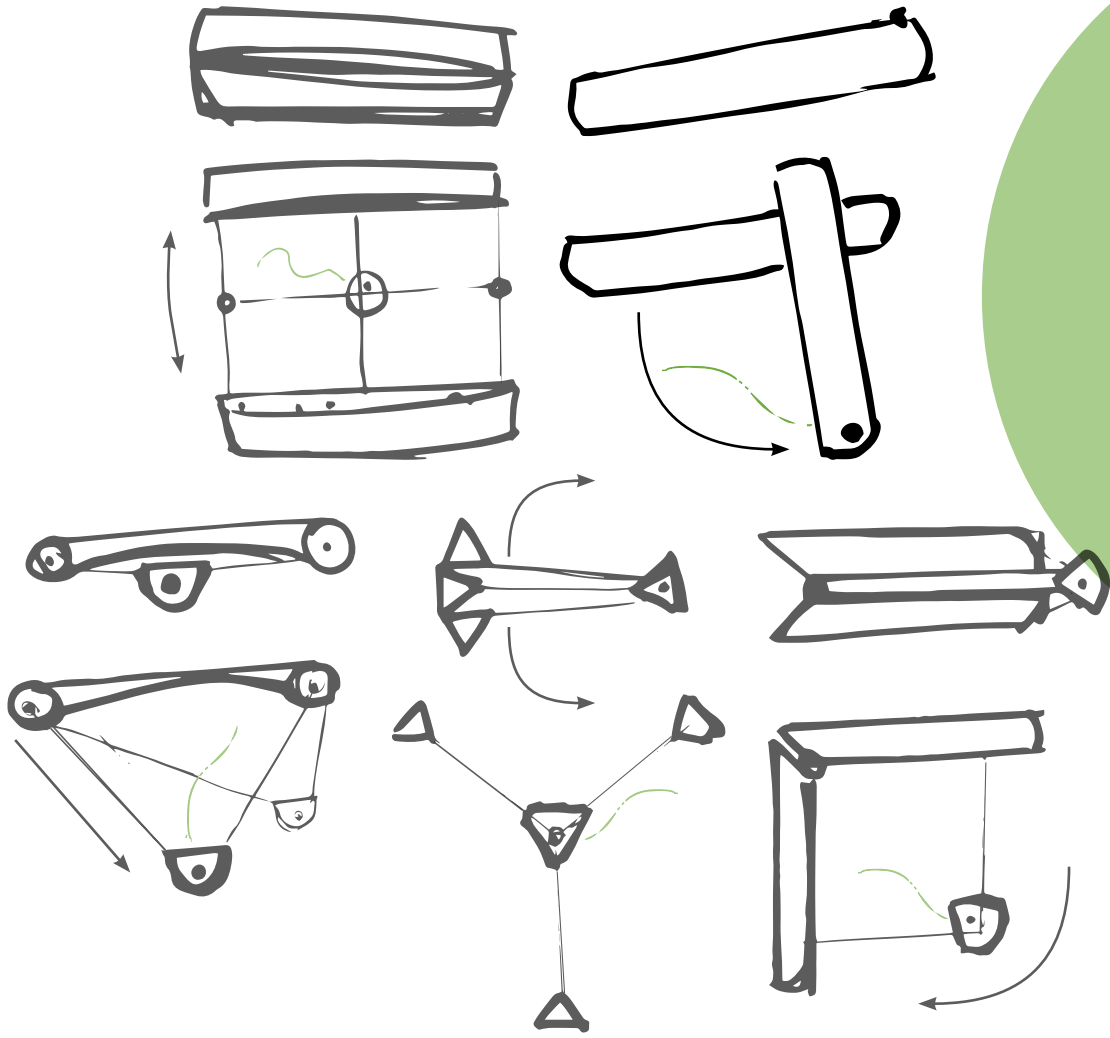
- ✗ Special software
- ✗ Special materials
- ✗ Just cuts

Penplotter



- ✗ Big
- ✗ Software not userfriendly
- ✗ Looks so technical
- ✓ Every material

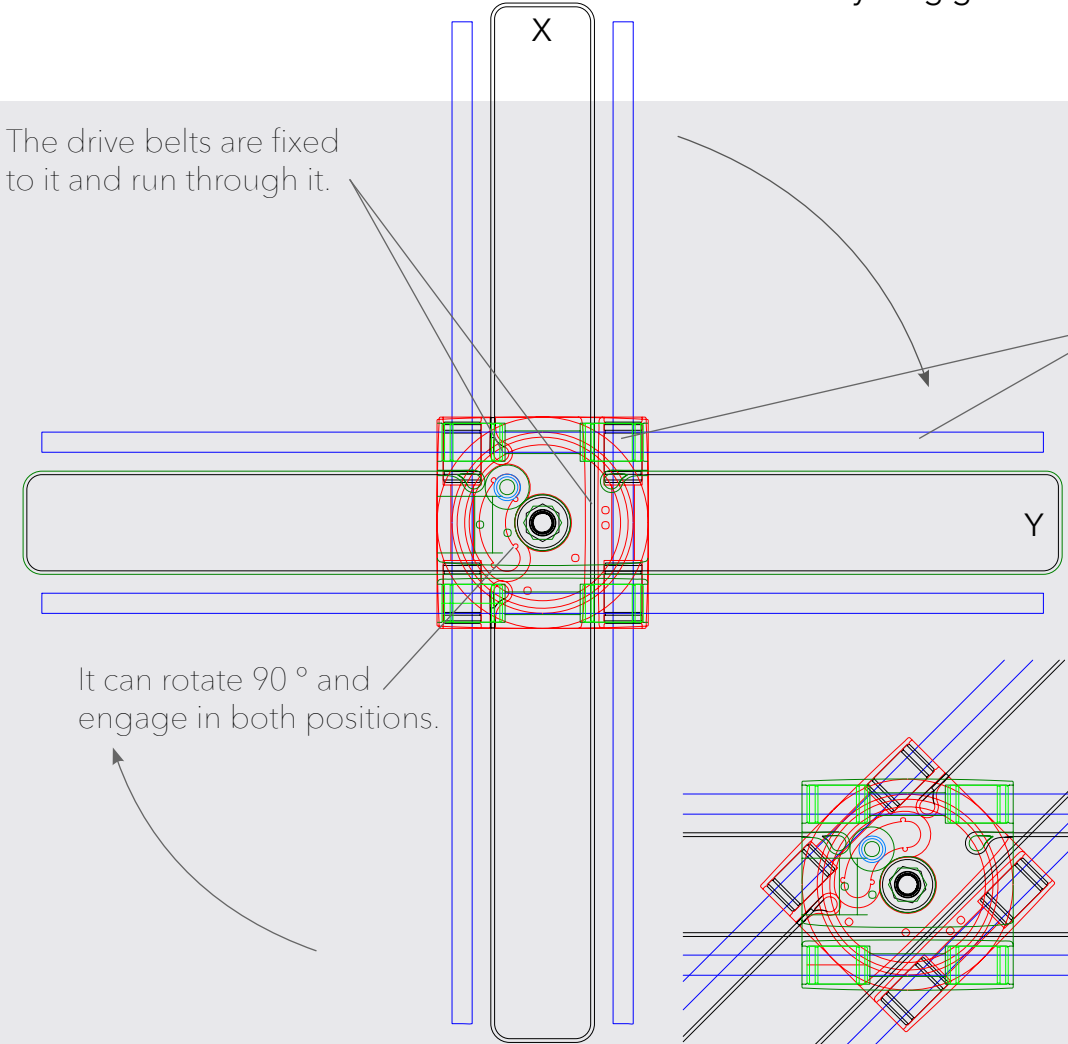




Reduce size

Design

The center of the machine is the heart.
Everything goes through it.

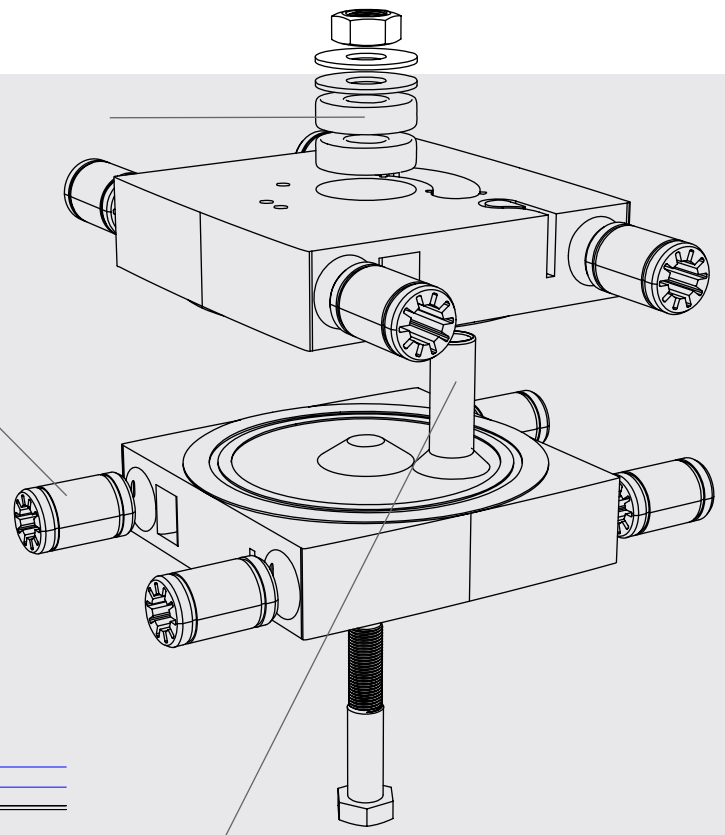
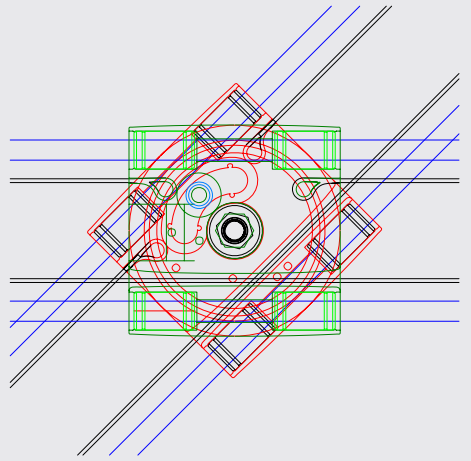


The drive belts are fixed to it and run through it.

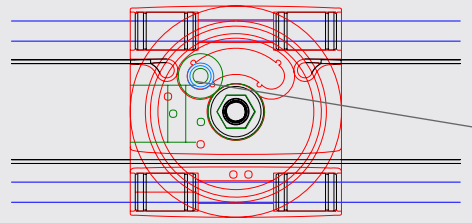
It can rotate 90° and engage in both positions.

It is stored by ball bearings.

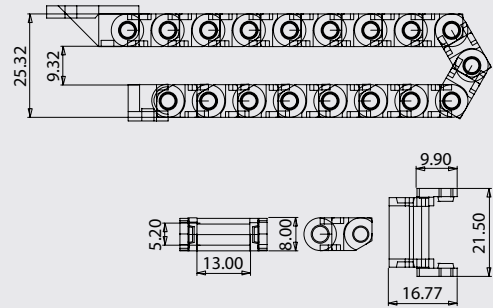
It is the connection between the two axes (X,Y). It also slides on them.



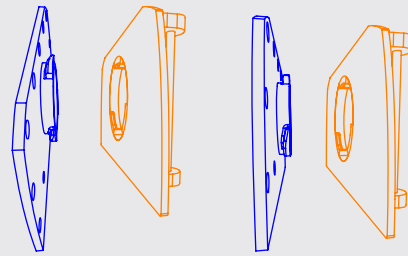
Eight cables run through it.



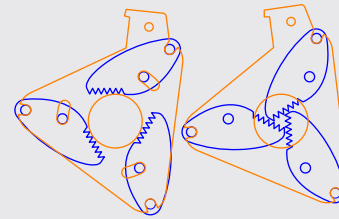
Parts that were made To enable working design



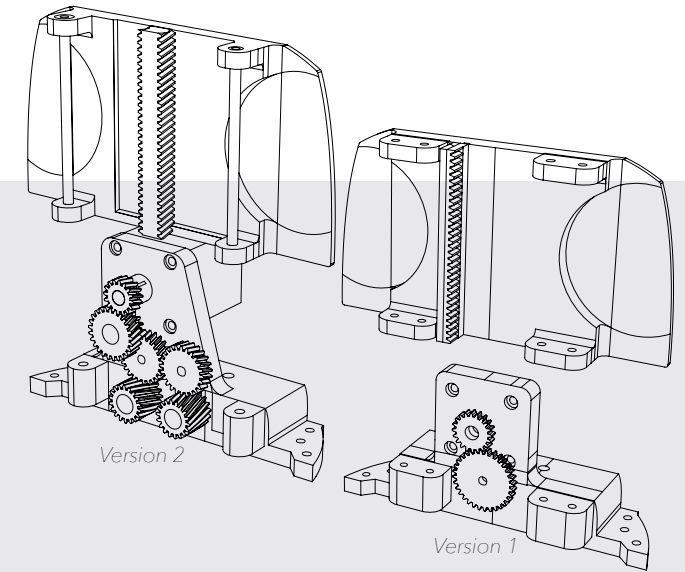
A completely new energy chain has been designed that only bends over 3 limbs and exactly meets the conditions. 4 versions were tested.



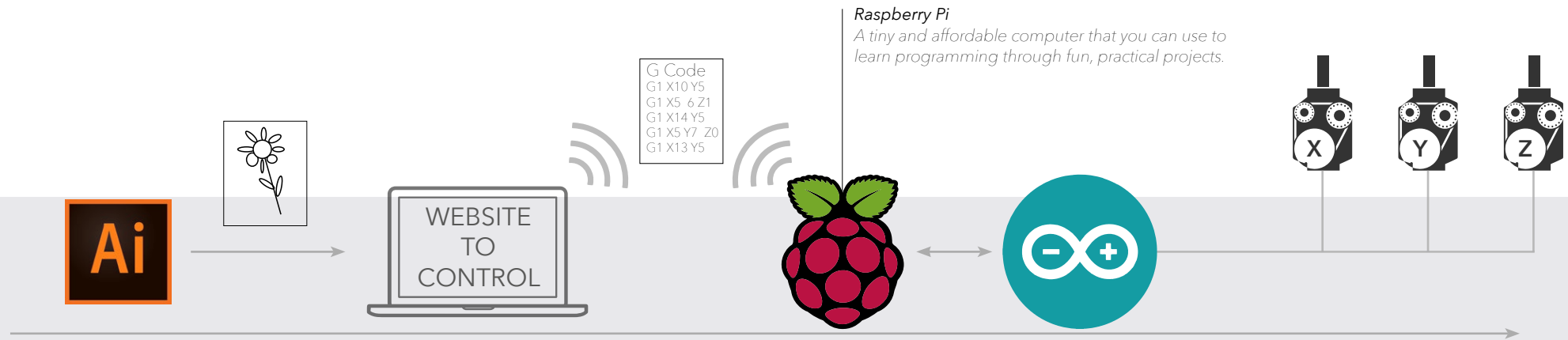
A bayonet catch that allows not only the current head to use. 3D printing extruder cutting or milling heads are conceivable and in planning.



The current head has a rosette closure which ensures that the tool is always centered.



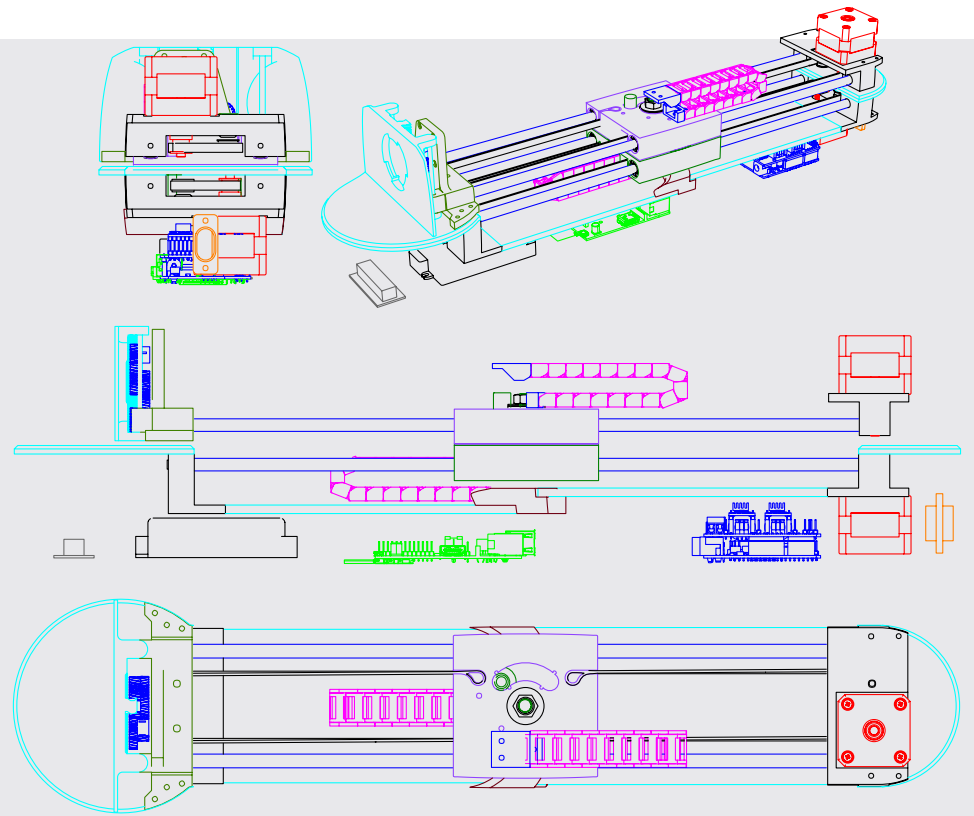
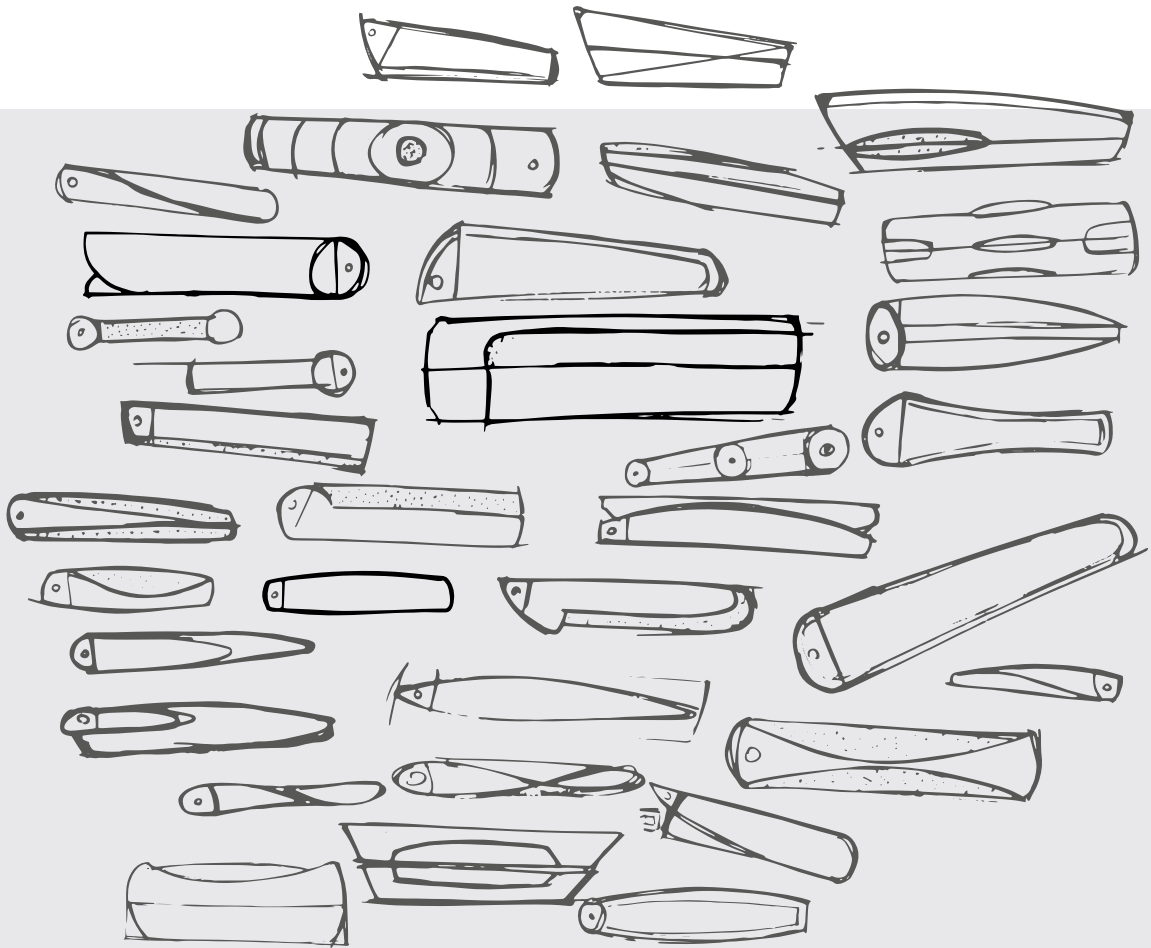
The Z axis was completely reworked 2 times. The version 1 was not functional. Version 2 has helical gear and is lifted by double rack gears to make it quieter. A 2:1 transmission was developed.

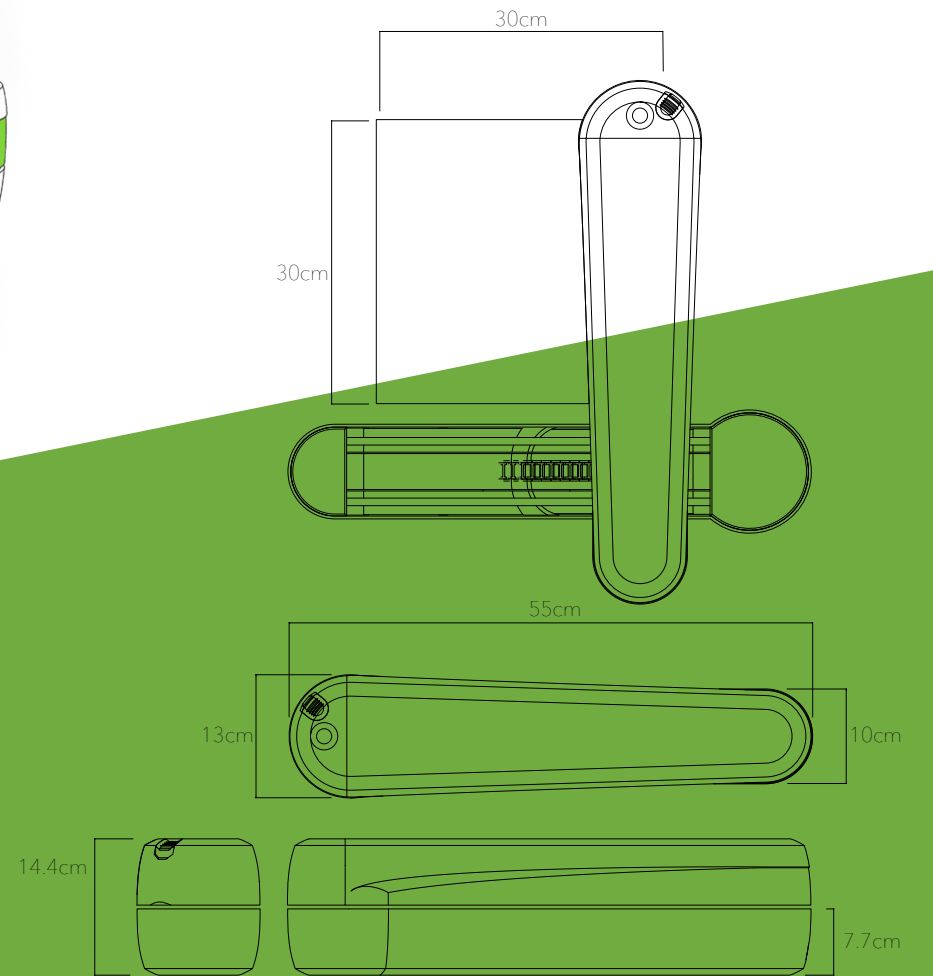
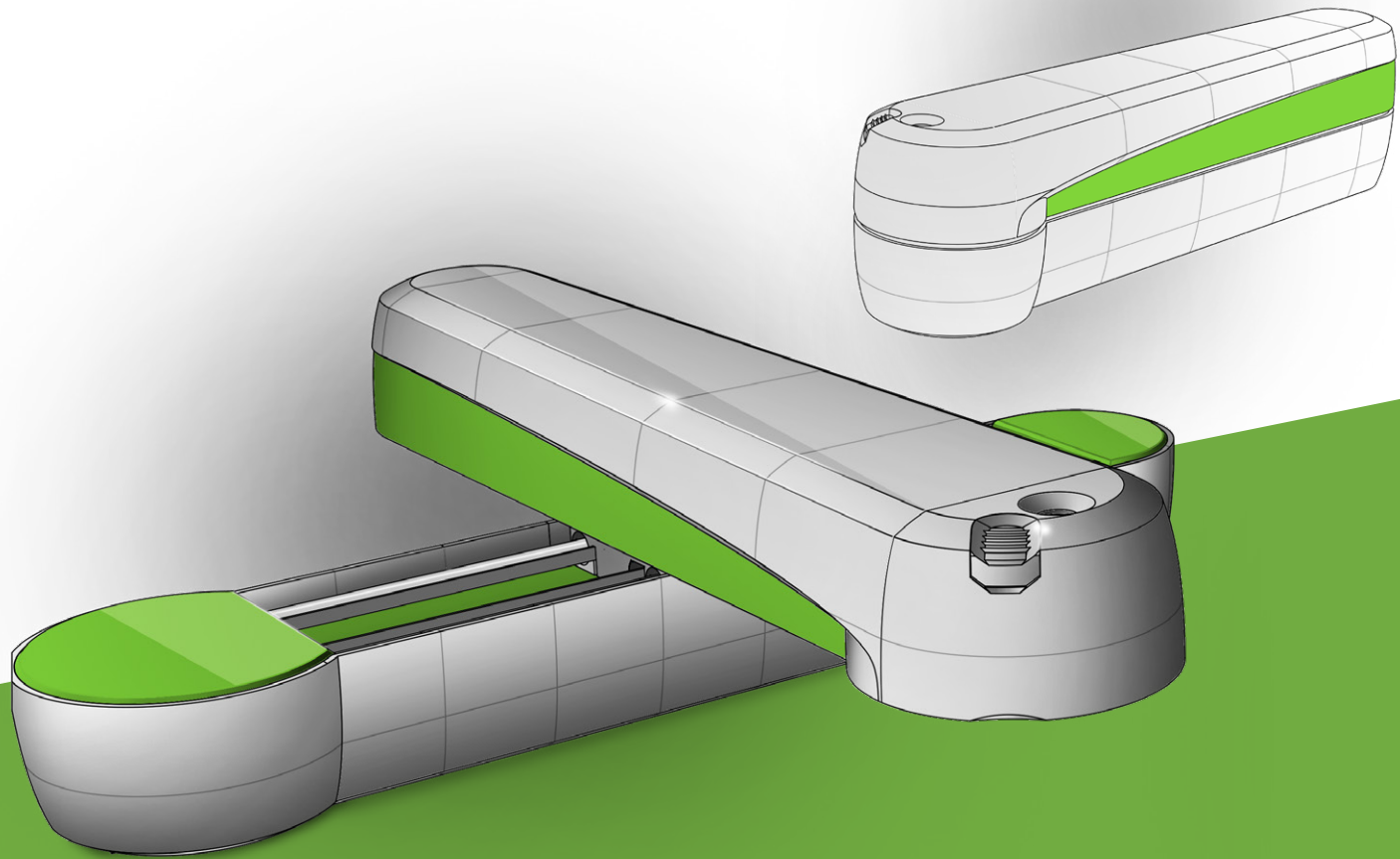


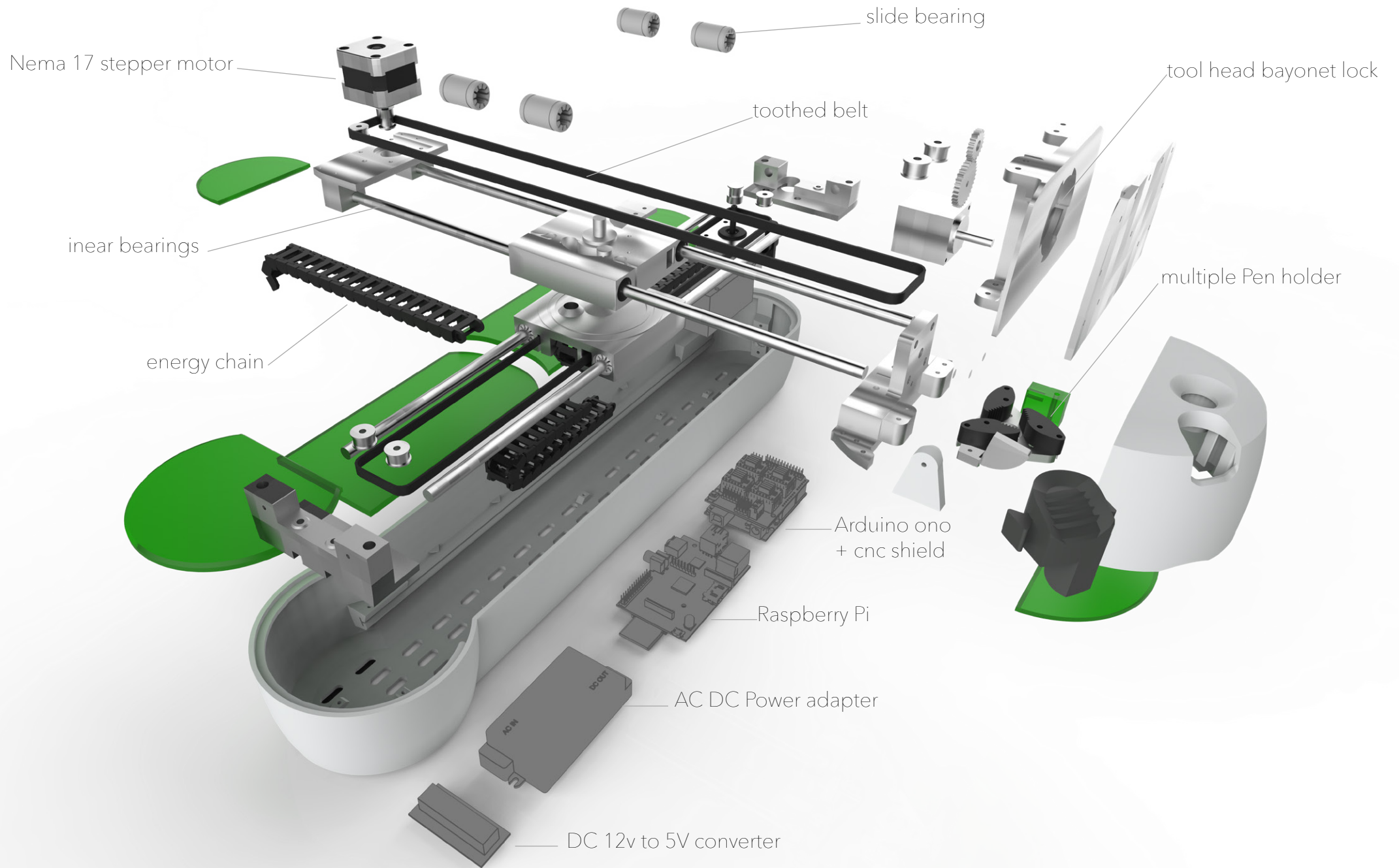
Raspberry Pi
 A tiny and affordable computer that you can use to learn programming through fun, practical projects.

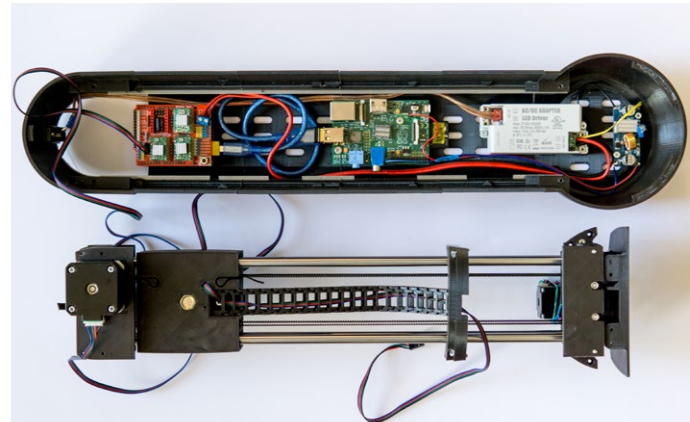
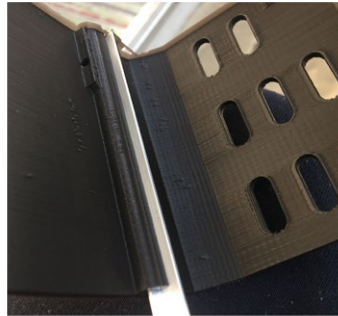
The screenshot shows the 'pingju' web interface. On the left, there is a control panel with buttons for 'Z+', 'Z-', 'Y+', 'Y-', 'X+', and 'X-'. Below these are 'Go Home (Y0 X0)', 'Feed Rate: 2000', and 'Distance: 10' settings. A 'Zero Machine (392)' is selected. The main area features a 'Gcode Preview' window showing a 3D model of a part with coordinate axes. At the bottom, there are buttons for 'Upload GCODE', 'Umwandeln', and 'Pingju Go!'. On the right side of the interface, there are buttons for 'Jscut CAM', 'Ausschalten', 'Shutdown', and 'CAM Software'. A 'Start' button is also visible.

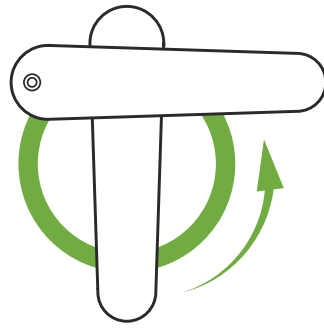
Software
 The control of the machine is based on GRBL.
 The web interface is based on web-Grbl.
 The autolevel function has been completed and implemented.





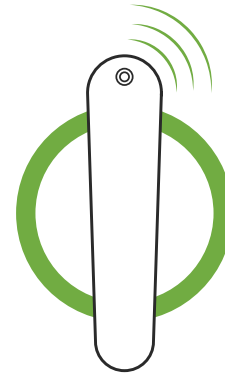






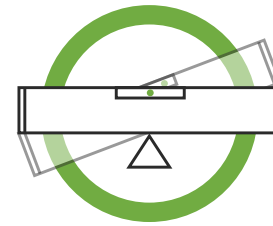
foldable

Pingju is foldable due to an ingenious hinge. This makes it transportable and at the same time it achieves a very large radius of action of 30x30 cm.



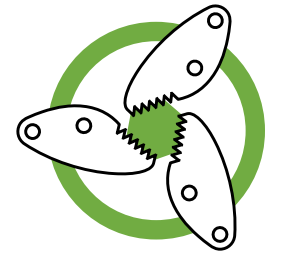
wireless controlling

Pingju is controlled via a web interface. One connects to the "Pingju WIFI" and can then control it conveniently. This gives the user maximum flexibility.



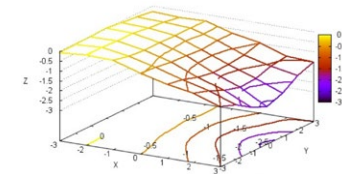
autoleveling function

Since Pingju behaves like a seesaw, the most elegant thing to do was to implement an auto level function. Now it interpolates the Gcode on the basis of a previously measured matrix.

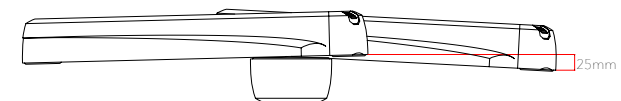


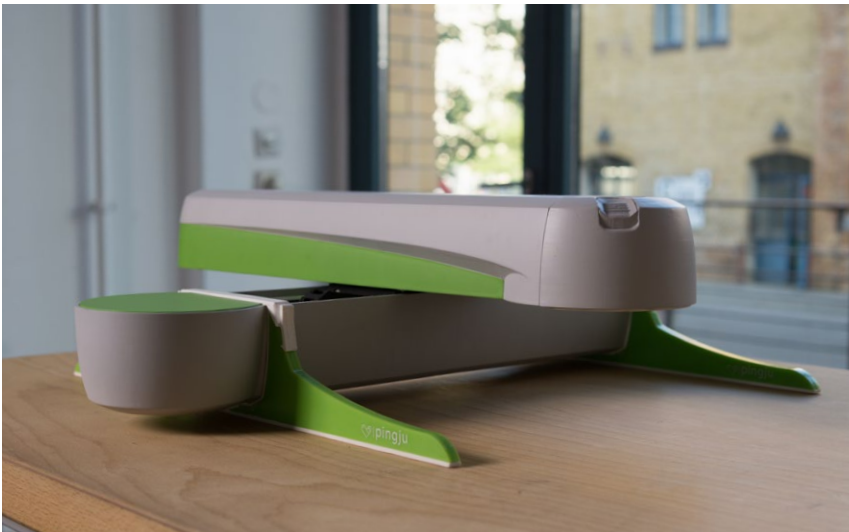
multitool

Whether with a ballpoint pen or sharpie, whether on paper or glass. Pingju draws, paints or writes on anything. This is achieved through sophisticated mechanics and precise construction.



Describes how far the head lowers to the work surface.





| pingju

A foldable plotter that can hold a variety of tools. Pens, cutting and 3D printing heads can be attached. This creates a mobile all-in-one office device. It is controlled via an intuitive web interface, so that the workflow is easy and no prior knowledge is required. Operation as easy as with a printer, only that everything can be "printed".

Constructed with: Rhino3D

Rendered with: Cinema4d

Model: 3D Print

Size folded: 14x55x14 cm, unfolded: 55x55x14cm

Work area: 30x30 cm

[vimeo.com/
292603947](https://vimeo.com/292603947)





Each of my projects
has a story that
I like to tell!

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